# Software requirements for Engineering Diffraction

(Reference instruments ENGIN-X@ISIS, Stress-Spec@FRMII, SALSA@ILL, Takumi@J-park) HC = Hot Commissioning UO = User Operations

#### Main instrument control

Item	Example Implemented	Must HC	Should HC	Must UO	Nice UO
Data Display					
2D live raw counts data for each detector (possibility change axis between $\lambda$ , 2 $\theta$ , ToF, d, Q)	Stress-Spec, ENGIN-X, SALSA	X			
1D live histogram display: integrated intensity over all detector area vs ToF ( $\lambda$ , d, Q) (for each detector)	Stress-Spec, Takumi	X			
1D live histogram of ROI with integrated counts vs ToF ( $\lambda$ , d, Q, 2 $\theta$ )	Takumi	X			
Correction of the live detector data for distortions, efficiency, calibration			Х		
Incident beam spectrum		Х			
Plot of SE parameters (temp, stress, position, etc.) as a function of time	Stress-Spec, ENGIN-X	X			
Visualization of the positioning system status			Х		
Transformation of engineering SE parameters to strain, stress, etc.	Stress-Spec, ENGIN-X, SALSA, Takumi	X			
Way to compare histograms (fix display of pattern in specific state to see current change)			X		
Save detector and 1D histogram images					Х
Region of interest (ROI) selection		Х			
Remote access to live data		X			
Under the Hood		X			
All relevant EPICS information saved in NeXuS		Х			
Sample, user, experiment information in NeXuS		X			
Logbook of entire experiment including instrument configuration, beam status and SEE		X			

parameters				
Scripted Instrument Interface				
Driving motors, setting limits, offsets		Х		
Changing SEE parameters		Х		
Reading SEE parameters		Х		
Counting for time, monitor, counts, charge		Х		
Simplified experiment planning		Х		
Continuous driving while counting (sweep)		X		
Loops, if-then		Х		
Script simulation		Х		
Quick change of instrument setups (SE, high/low resolutions, multiplexing)		X		
GUI Interface				
Driving motors, setting limits, offsets		Х		
Changing SEE parameters		Х		
Reading SEE parameters		Х		
Counting for time, monitor, counts, charge		Х		
Read of pre-measured 3D coordinates and scanning path planning (ex. SScanSS)	ENGIN-X	X		
Adjustment and visualization of positioning system (hexapod, robot, tables, etc.)			X	
Quick change of instrument setups (SE, high/low resolutions, multiplexing)			X	
Simplified experiment planning (experiment tree structure)		X		
Experiment simulation for multiplexing (predict overlap, adjust the MC speed)			X	
Continuous driving while counting (sweep)		X		
Instrument Live feedback				
Choppers frequency and position (measurement mode)		X		
Beam power monitor	Stress-Spec, SALSA	X		
SEE parameters	Stress-Spec		X	
Sample position status	Stress-Spec		X	

## **Special instrument control**

Item	Already Implemented	Must HC	Should HC	Must UO	Nice UO
Laser/Optical alignment of sample positions			Х		
SE calibration procedure (deformation rig)				Х	
Simple real-time data analysis (individual peak fitting) with active feedback to control SE				Х	
SSCANSS or related sample positioning system			Х	Х	

### Data reduction general

Item	Already Implemented	Must HC	Should HC	Must UO	Nice UO
Full access to raw events data in Mantid and as NeXuS		Х			
Full access to SE and instrument status tags events data in Mantid and as NeXuS		Х			
Multiplex data reductions		Х			

### Data reduction conventional engineering

Item	Already Implemented	Must HC	Should HC	Must UO	Nice UO
Correction for detector distortions, efficiency, calibration		Х			
Normalization of each event to incident beam		Х			
Background subtraction			Х		
Variable binning (SE parameters, time, ToF, Q, d, manual)		Х			
Extraction of 1D I(Q), I(d)		Х			
Extraction of 2D I(ToF, 20), I(ToF, d)		Х			
Help algorithms (peak finder, prediction of relevant peaks – sample information)		Х			
Automatic reduction mode				Х	
Reload reduction for reevaluation				Х	
Save to ASCII (Q, I, FWHM, Dd/d, ToF-d matrix)		Х			

## Data reduction special engineering

Item	Already	Must	Should	Must	Nice
	Implemented	HC	HC	UO	UO
Extraction of $d_0$ for multiplexing technique (guess based on sample information, manual)		Х			

## Data acquisition and storage

Item	Already Implemented	Must HC	Should HC	Must UO	Nice UO
Data Acquisition Parameters					
Time (Global Clock)		X			
Proton Pulse		X			
Chopper disks position		X			
Beam Monitor		X			
Detectors		X			
Slit position (opening)		X			
Motor axis positions		X			
SEE parameters					
Temperature		X			
Load		X			
Motor position		X			
Vacuum			X		
Special requirements					
Off-beam SEE parameters for long term experiments (stand-alone mode)		X			
Data storage					
Max. data rate detectors (day 1)	550 Mb/s				
Data format					
ASCII		X			
HTML5					Х
NEXUS		X			