

# ESS spoke cavities tuning

**N. Gandolfo**

*On behalf of ESS Spoke cryomodule team*

**SLHiPP-4 – CERN – 15<sup>th</sup> May 2014**

# ESS spoke cavities tuning

---

## Outline

- Why do we need a tuner?
- How does look the design phase?
- ESS double spoke tuner, how does it work?
- Preliminary results at room temperature

# Why do we need a tuner?

## Main actions of a tuner (or Cold Tuning System)

- Tuning : Adjust and control the cavity resonant frequency during operation
- Detuning : In some failure case, it may be useful to detune the cavity in order to not let the beam interfere with it

## Identified perturbations to compensate

Perturbations	Speed	Repetition	Amplitude
<b>Fabrication incertitude</b>	Static	Once	Large (~10s kHz)
<b>Cooling down Incertitude</b>	Quasi-static (~ hours)	Once	Large (~10s kHz)
<b>Pressure variations</b>	Slow (~ seconds)	Random / hours	Medium (~100s Hz)
<b>Lorentz forces</b>	Fast (~ milliseconds)	Each beam pulse	Medium (~100s Hz)
<b>Microphonics</b>	Fast (~ milliseconds)	Random / continous	Medium to small (~100s Hz to ~10s Hz)

# How does look the design phase?

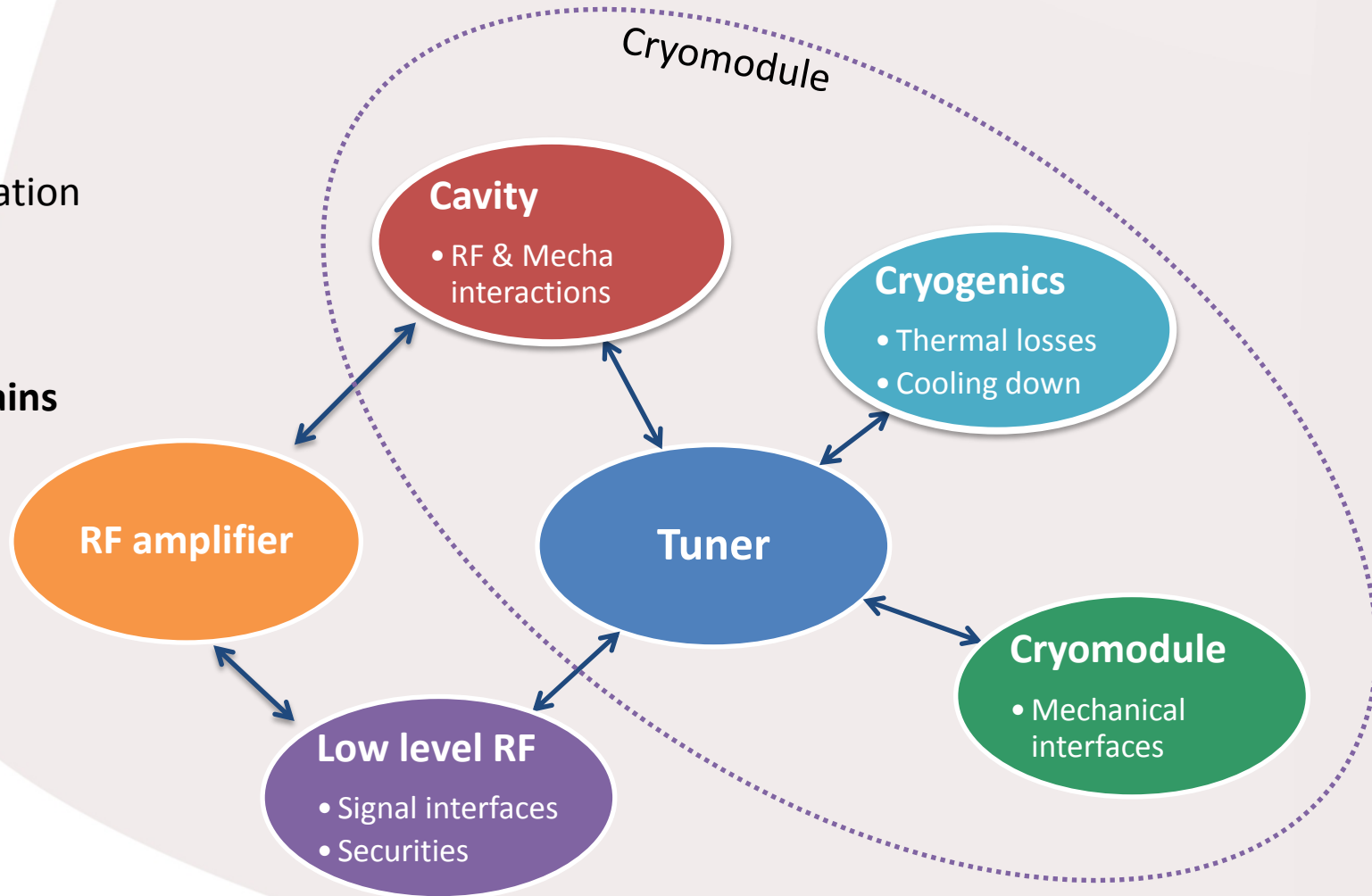
## Tuner interaction overview

### Different skills

- Electronics
- Mechanics
- Instrumentation
- Simulation
- And more...

### Multiple domains

- Vacuum
- Cryogenics
- RF
- Magnetic
- Control
- And more...

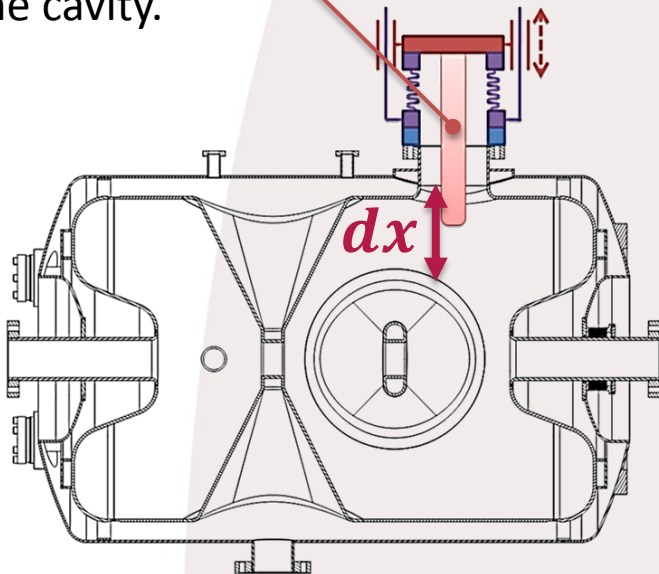


# How to tune?

## Two ways of tuning well identified

### By insertion

...of a superconducting plunger inside the cavity.

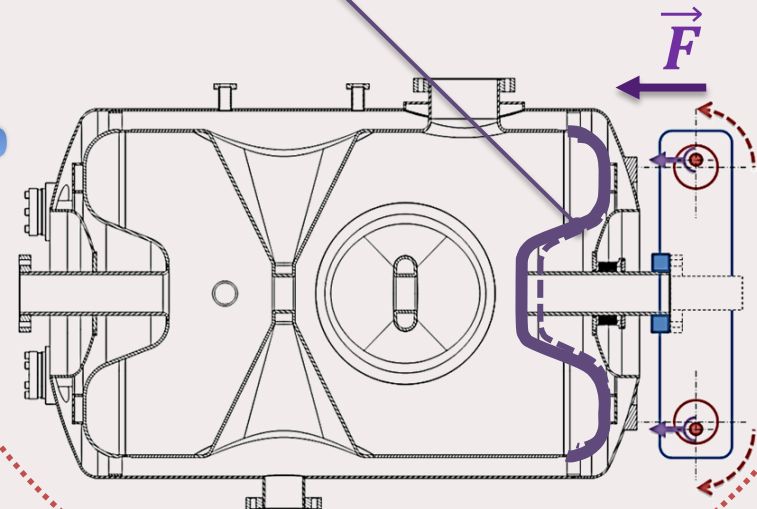


- No risk to damage the cavity
- Not mature yet
- Additional risk of pollution / quench
- Clean room assembling
- Must be integrated to LHe circuit
- Fast tuning seems to be an hard task

### By deformation

...of a local area of the cavity.

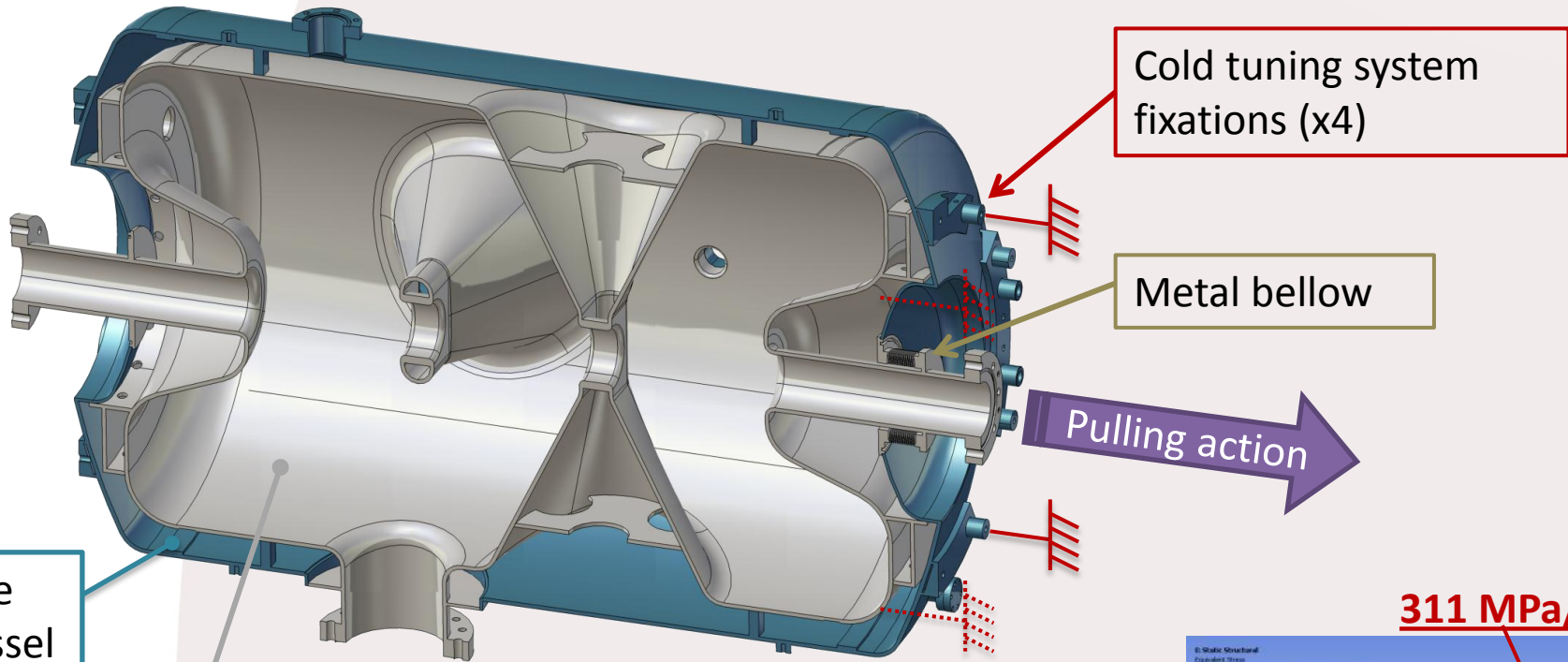
VS.



- No interaction with inside of the cavity
- Reliable
- Cooling down is long
- Additional space along the beam axis
- High forces involved
- Risk of plastic deformation of the cavity

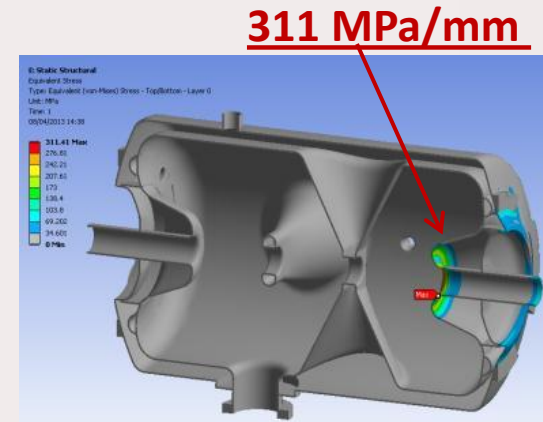
# Design study : Cavity parameters

## Double spoke cavity



## Cavity RF/Mecha computation results

- Tuning sensitivity : **135 kHz/mm**
- Cavity stiffness : **20 kN/mm**
- ➔ “Tuning challenge coefficient” : **148 N/kHz**
- Max displacement @2K (400 MPa) : **1.28 mm**



## Cavity frequency requirement

- $Q_L = 1.77e+5$
- Resonant frequency = 352.2 MHz
- Cavity bandwidth = 1,990 Hz
- ➔ Looking for a resolution of at least 100 Hz (0.74  $\mu\text{m}$ )

## Sensitivity to Helium bath pressure fluctuation

$K_p$ without CTS (free ends)	<b>+16.5 Hz/mbar</b>
$K_p$ with greatly stiff CTS*	<b>+26.0 Hz/mbar</b>

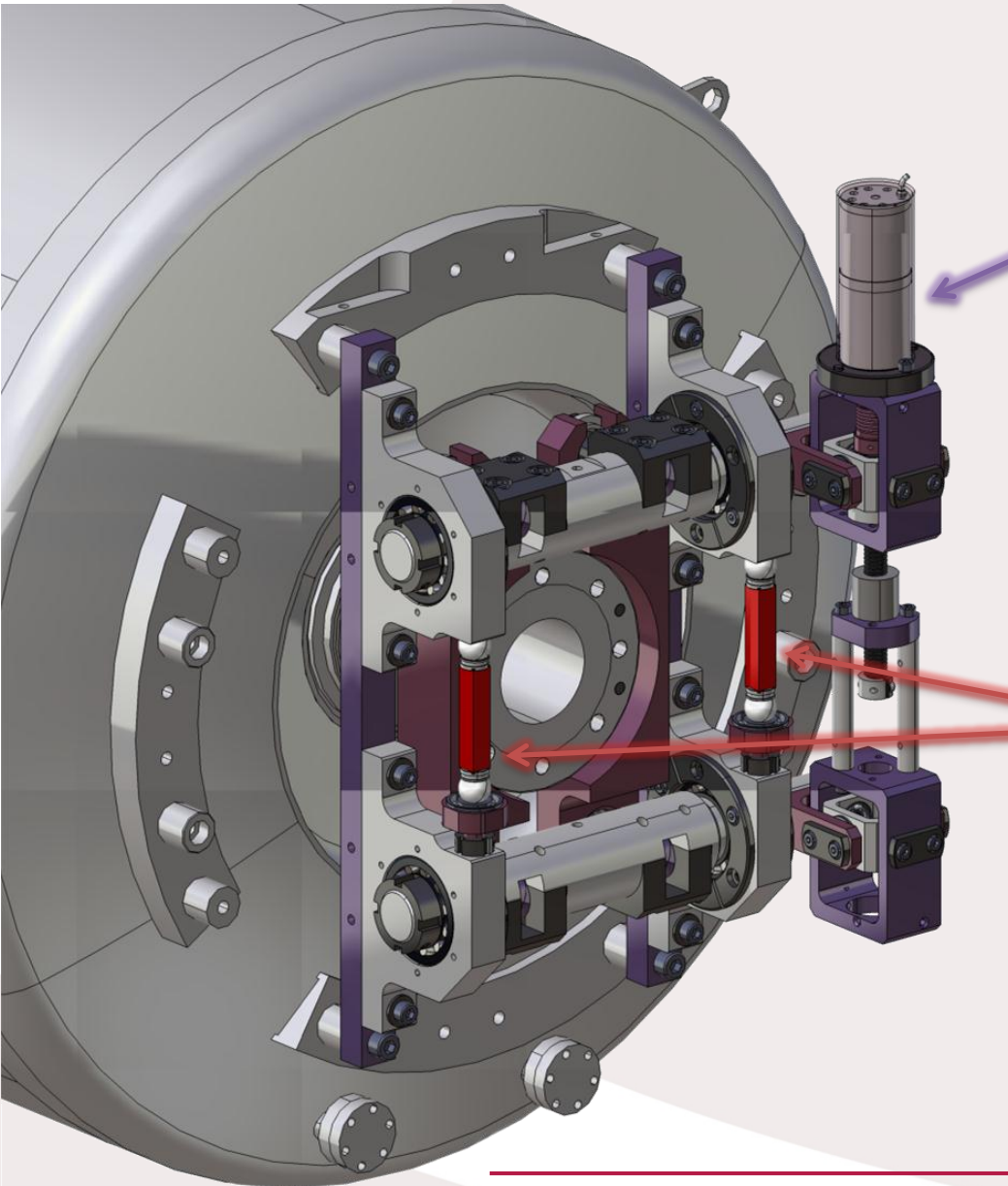
\*The beam tube is connected rigidly to the helium vessel at the level of the 4 CTS supports (along the beam axis)

*Notice the Lorentz forces detuning are small in regard to the cavity bandwidth*

## Sensitivity to Lorentz forces detuning

For 9 MV/m		
$K_L$ without CTS (free ends)	<b>-5.13 Hz/(MV/m)<sup>2</sup></b>	$\Delta f = -415 \text{ Hz}$
$K_L$ with stiff CTS	<b>-4.4 Hz/(MV/m)<sup>2</sup></b>	$\Delta f = -356 \text{ Hz}$

# ESS Double Spoke tuner



## Slow tuner

Main purpose : Compensation of **large** frequency shifts with a **low** speed

Actuator used : Stepper motor with planetary gearbox (1:50)

## Fast tuner

Main purpose : Compensation of **small** frequency shifts with a **high** speed

Actuator used : Piezoelectric actuators (no load displacement :  $\sim 50 \mu\text{m}$  @ RT)

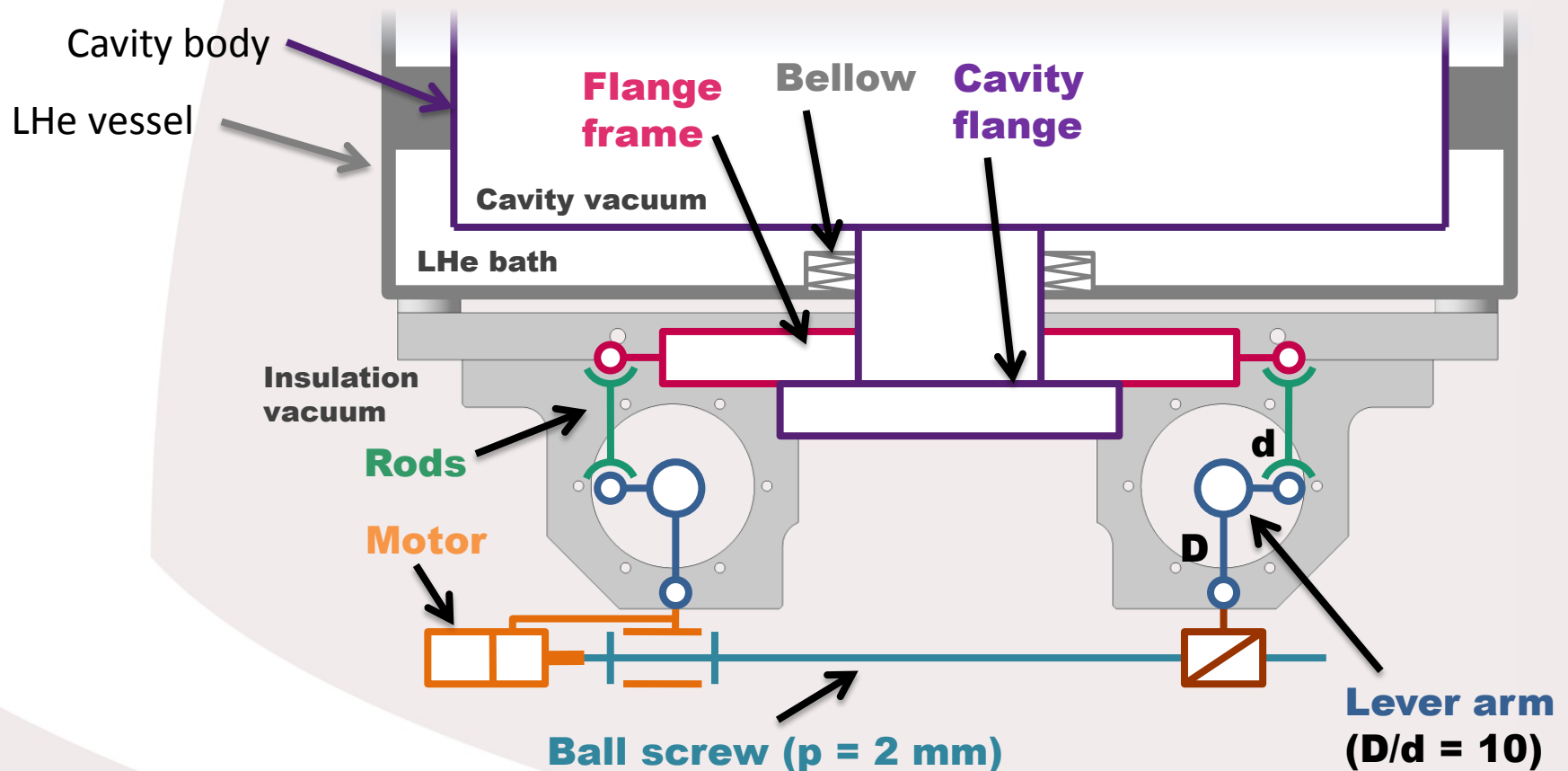




# Slow tuner

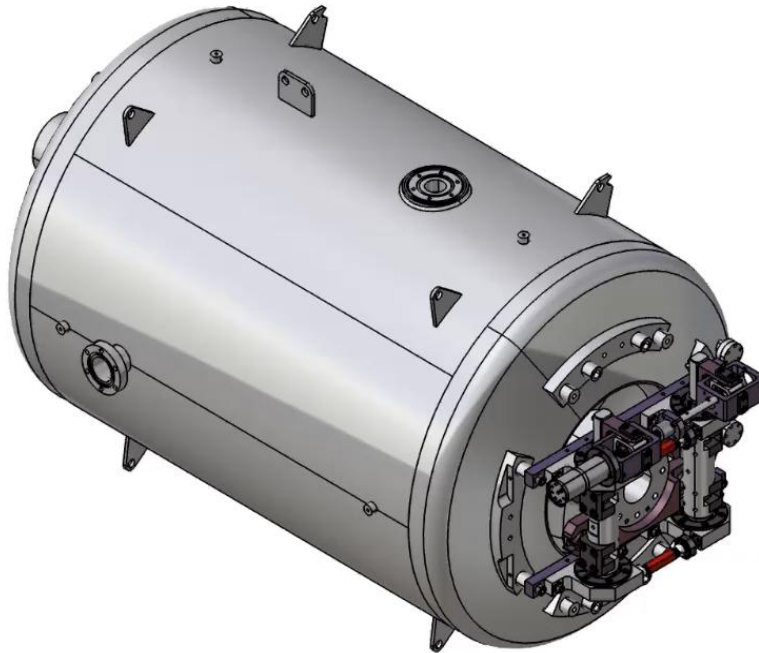
## Slow tuner principle

A ball screw system driven by a **stepper motor** acts on a **double lever arm** mechanism to provide a significantly reduced displacement of the **cavity flange** along the beam axis.



# Slow tuner

## Slow tuner in motion



Cavity sensitivity

- 135 kHz/mm

CTS tuning range

- 135 kHz

Cavity stiffness :

- 20 kN/mm

CTS stiffness estimated :

- 110 kN/mm

CTS theoretical resolution :

- 10 nm/step (full step mode)

Final Tuning resolution :

- 1.14 Hz/step (full step mode)

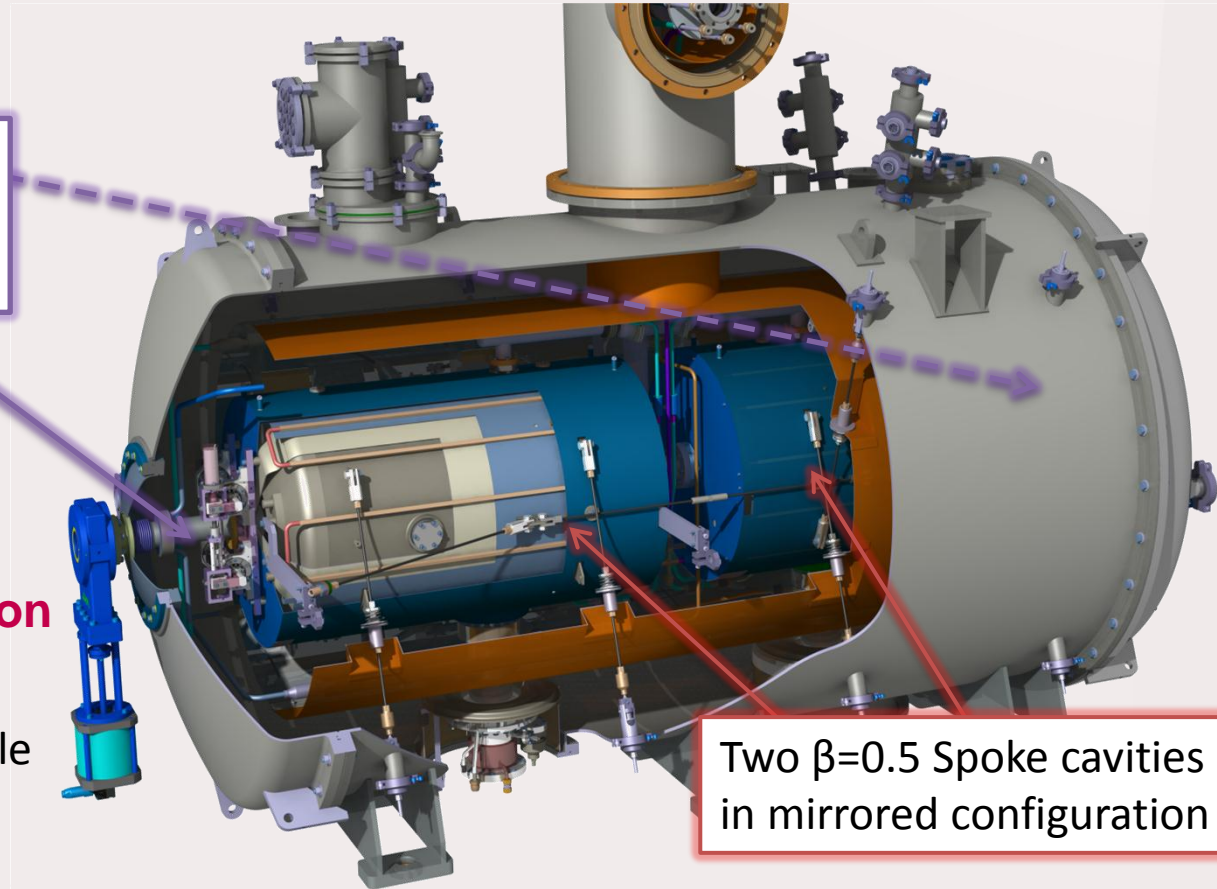


z  
x-y

# Cryomodule integration

## ESS Spoke cryomodule

CTS are located on each side  
 of the cryomodule  
 Additional mass : 2x 14 kg



## Transmission & motorization

Two options identified :

- From outside the cryomodule
- From inside the cryomodule

Two  $\beta=0.5$  Spoke cavities in mirrored configuration

### Inside advantages

- **Less thermal losses** (if the motor is only powered when it is running)
- **Less interaction with cryomodule :**
  - Design // Risks // Assembly

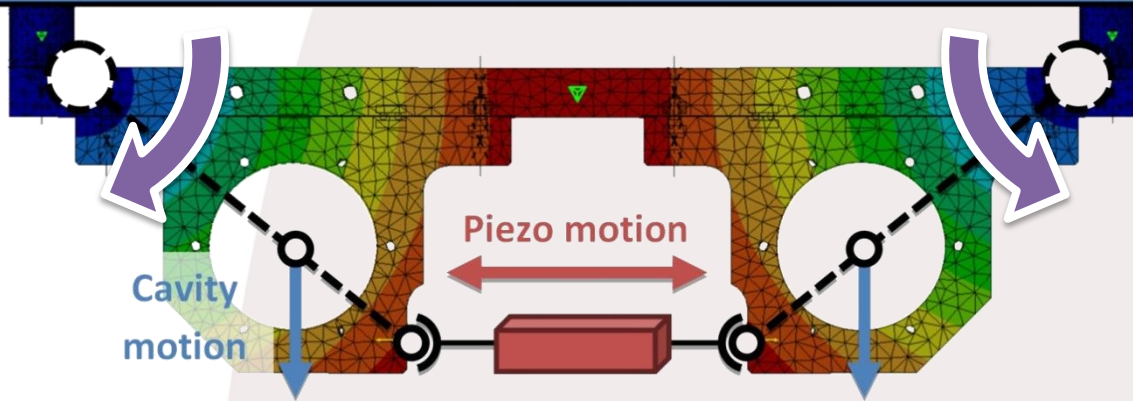
**Vs.**

### Outside advantages

- **Maintenance of the motor**
- Motor is cheaper (but cost for additional parts must be taken in account)

# Fast tuner

LHe cavity tank (considered as immobile and non-deformable)



## Fast tuner principle

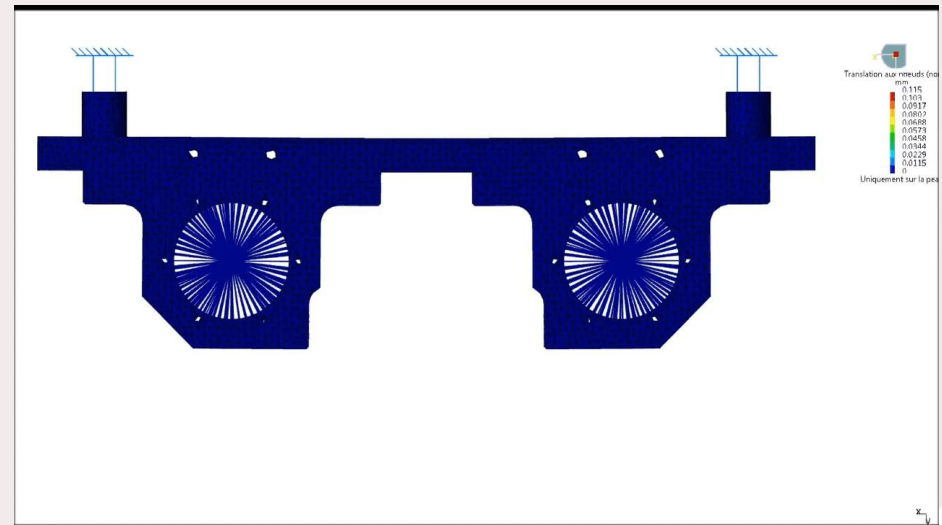
- Rigid lever arm concept
- 38% of dual piezos motion is transmitted along the beam axis
- Quasi independent from the slow tuner action

## About preload force

Value targeted : ~20 MPa (2kN)

Comes from 3 identified sources :

- Thermal shrinks (small contribution)
- Slow tuner (small contribution)
- Manual preloading during assembly



# Fast tuner

## Piezo assembly

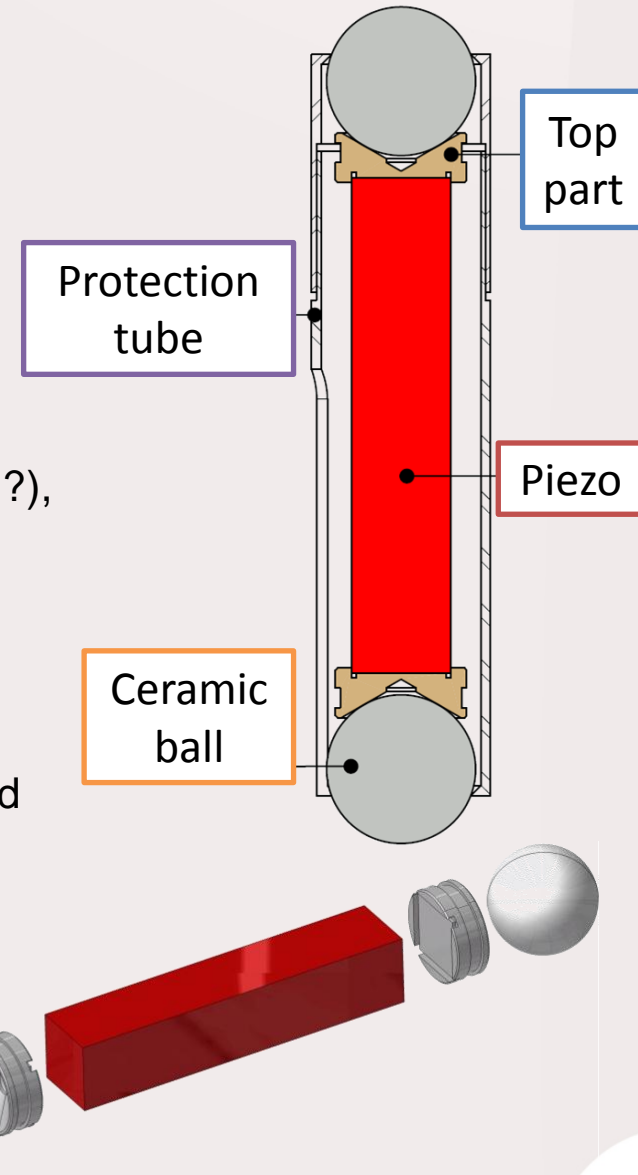
Two different manufacturers have been selected to compare performances : Noliac & Physik Instrument.

Main differences between Noliac & PI is the way to build stacks :

- Noliac build multilayers actuators of 2 mm height, then stack them with glue, **this allow fabrication of very long piezos** (>100 mm)
- PI **build directly multilayers** of defined height (more reliable ?), but 36 mm max from catalogue

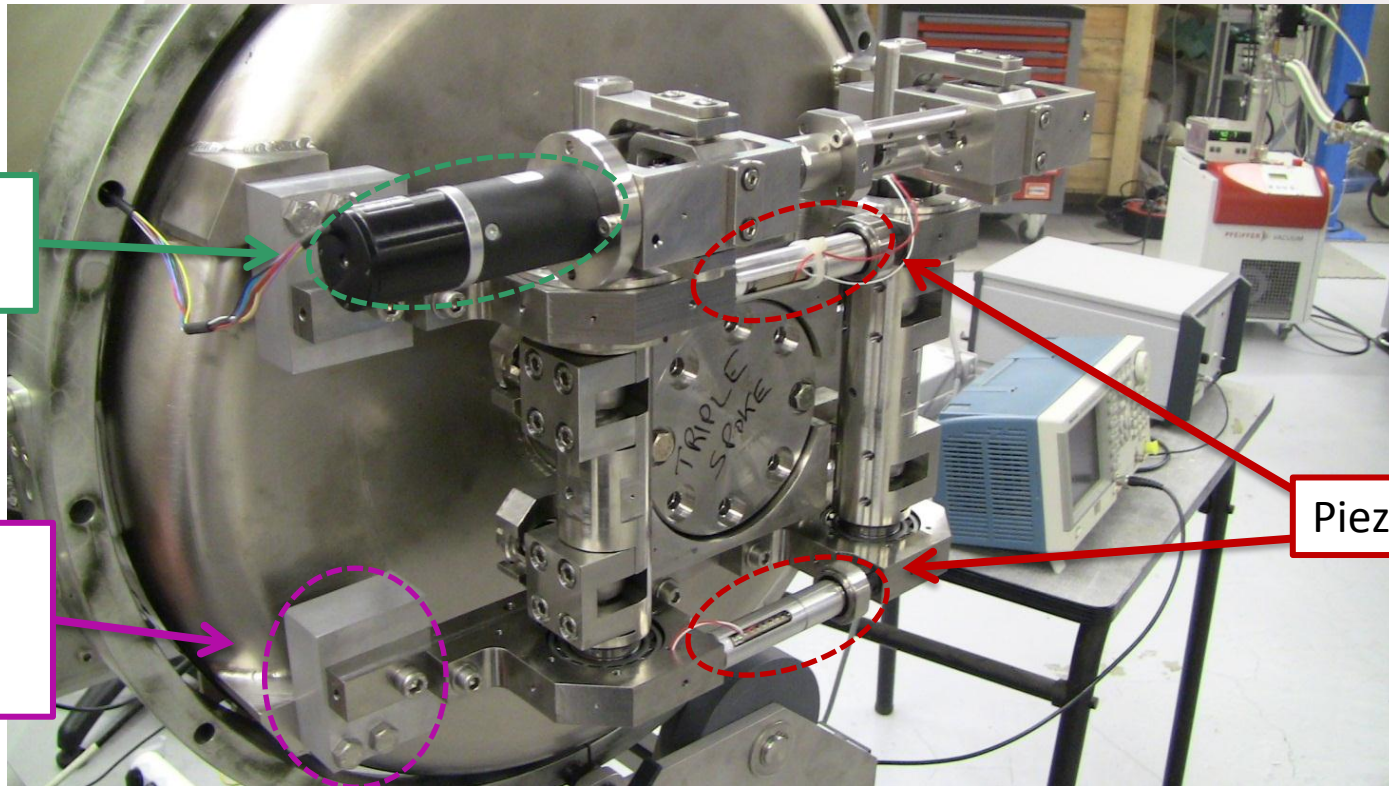
### Tricks and Tips:

- Think to **attach the cables rigidly** to a fix part of the tuner to avoid over stress at the welding of the piezo electrodes
- Ring stacks piezo actuators exist but if they seem more adapted to interface with spherical joints, they can be also **much more expensive** (up to 3 times for similar performances)



# Preliminary results (at room temp.)

## Tuner put on a triple spoke resonator (EURISOL prototype)



Stepper motor

Aluminum adaptation parts (x4)

Piezos

### Similar cavity parameters

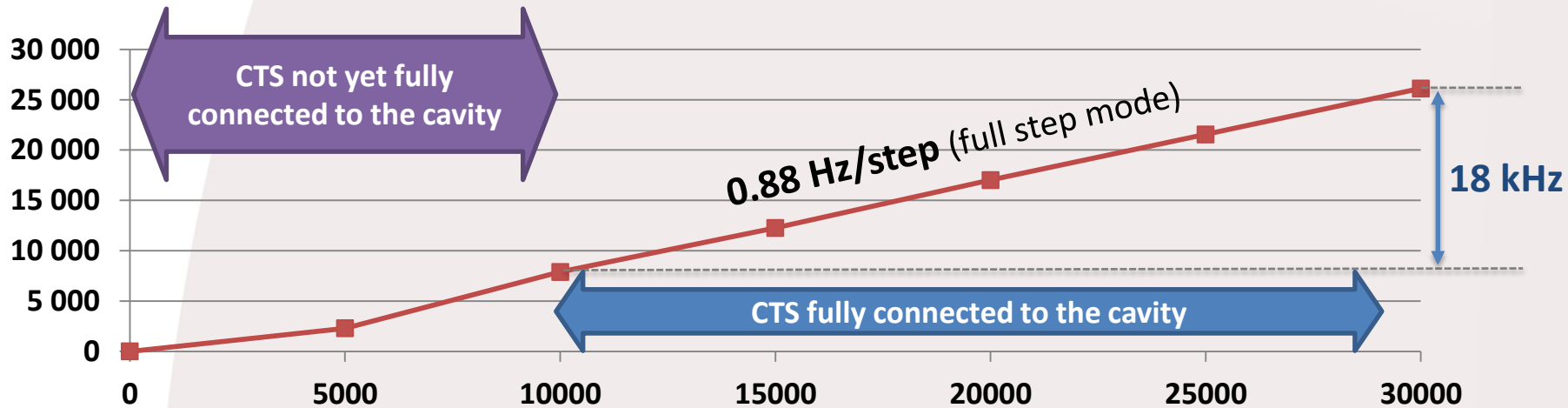
	ESS spoke cavity	Triple spoke cavity
Stiffness	20 kN/mm	19.3 kN/mm
Tuning sensitivity	135 kHz/mm	180 kHz/mm

# Preliminary results (at room temp.)

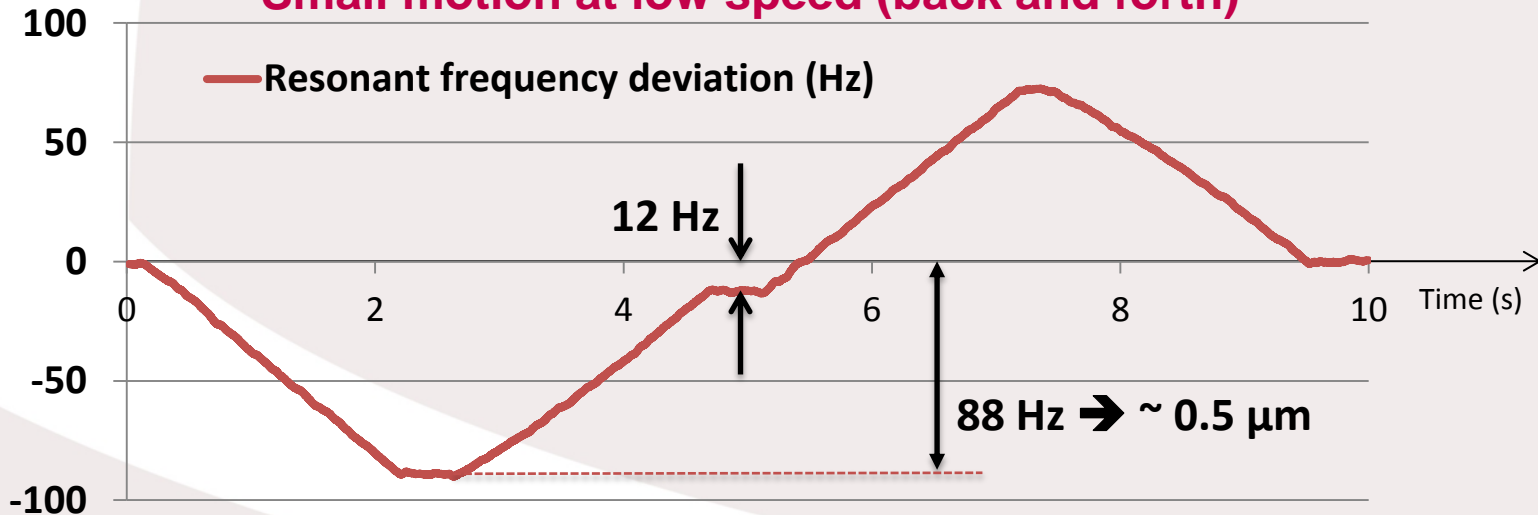
## Slow tuner test on triple spoke cavity

Max range limitation :  
@300K : 30k steps

Frequency shift (Hz) Vs motor displacement (step)



## Small motion at low speed (back and forth)

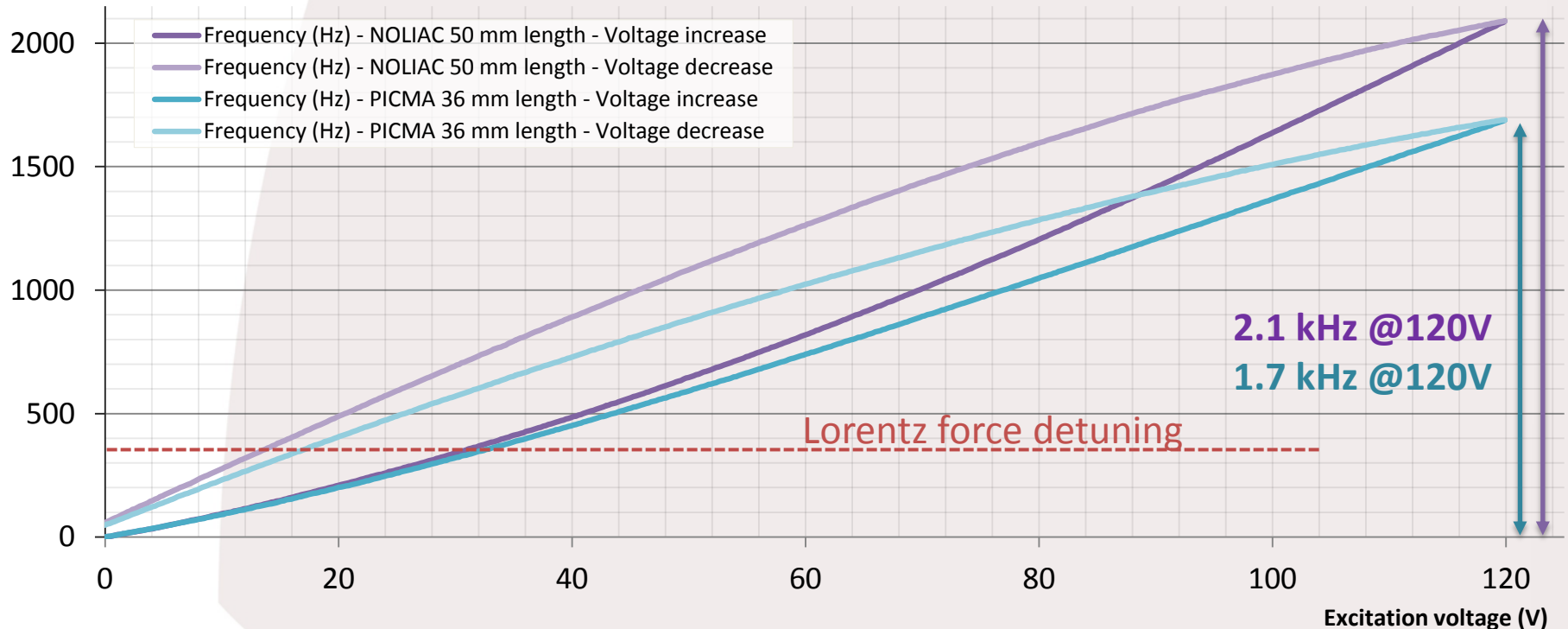


# Preliminary results (at room temp.)

## Fast tuner test

Relative frequency (Hz)

### Piezos tuning range measurement at room temperature



Reminder :

- Here the cavity sensitivity is 180 Hz/ $\mu\text{m}$  instead of 135 Hz/ $\mu\text{m}$  for double spoke
- At low temperature, piezo can be driven with full bipolar range [-120 V to +120 V]
- At low temperature, piezo stroke is expected to drop at around 25% from 300 K



## Actual tasks

- Make a cryogenic test @2K
- Improve the design thanks to the experience from prototypes
- Piezo cryogenic test campaign
- Preparing the mass production (Quality stuff, procedures, etc.)

## And also... one tricky issue is remaining

- Integration of system to disengage the tuner from the cavity if it get stuck

## Few personal feelings I want to share

- Slow and fast tuner linked together cause some interferences on both design and operation phases. Maybe a good thing would be to **physically separate** these two functions, especially when the cavity is very stiff.
- In the ESS spoke cavity case, maybe the piezo are not necessary (low LFD, high bandwidth) **BUT** they may significantly improve the slow tuner lifetime and performances with a smart control process.

☺ **Thanks you for your attention** ☺

piezos 50x10x10 mm Noliac :  
- 70  $\mu\text{m}$  @ 200 V  
piezos 36x10x10 mm PI:  
- 38  $\mu\text{m}$  @ 120 V

