

The Common Calibration Protocol and Neutron Quality Label for Neutron Strain Scanning Instrumentation

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Motivation

Background

Demand for access to Neutron Strain Scanners

Demand & complexity increase

Access limited & competitive

Measurement quality & instrument interchangeability

Harmonization of protocol and reporting → *NQL*

Neutron Quality Label (NQL)

Background



Neutron Quality Label

Quality standard for a **measurement/
specific setup** on neutron strain scanners

Obtained by following a series of **common
calibration measurements and reporting**

NQL and other standard

Background

VAMAS TWA20 &
RESTAND

Round robin activities → establish
neutron diffraction as reliable method for
residual stress measurement

ISO 21432:2019

General guidelines on how to perform
neutron diffraction for residual stress
measurement

Neutron Quality
Label (NQL)

Practical guideline to characterized setup
using common method i.e., samples &
protocol (+ how to report)



Neutron Quality Label

Template includes:
Instrument setup info
& measurement result

To reproduce
measurement on
other time/
instrument

The project

Background

Project → Development of possible methods to characterise particular setup of instruments →

Positional accuracy

Participants

Background

brightness²

Work Package 2

D2.1 Preliminary report on engineering



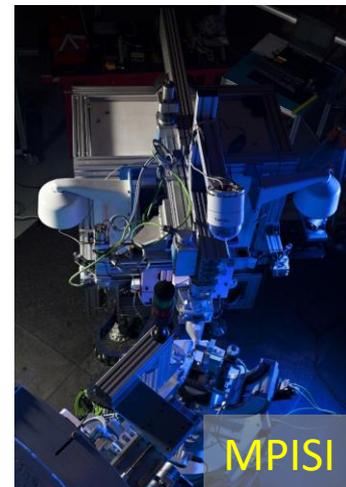
SALSA



ENGIN-X



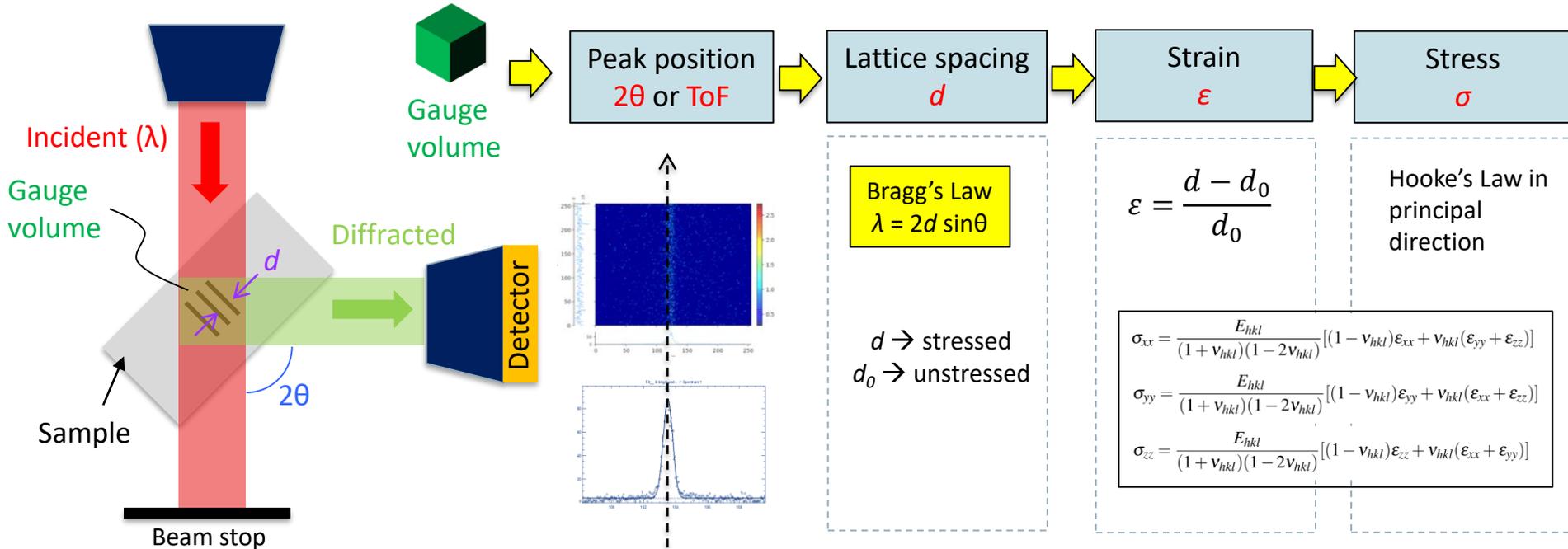
STRESS-SPEC



MPISI

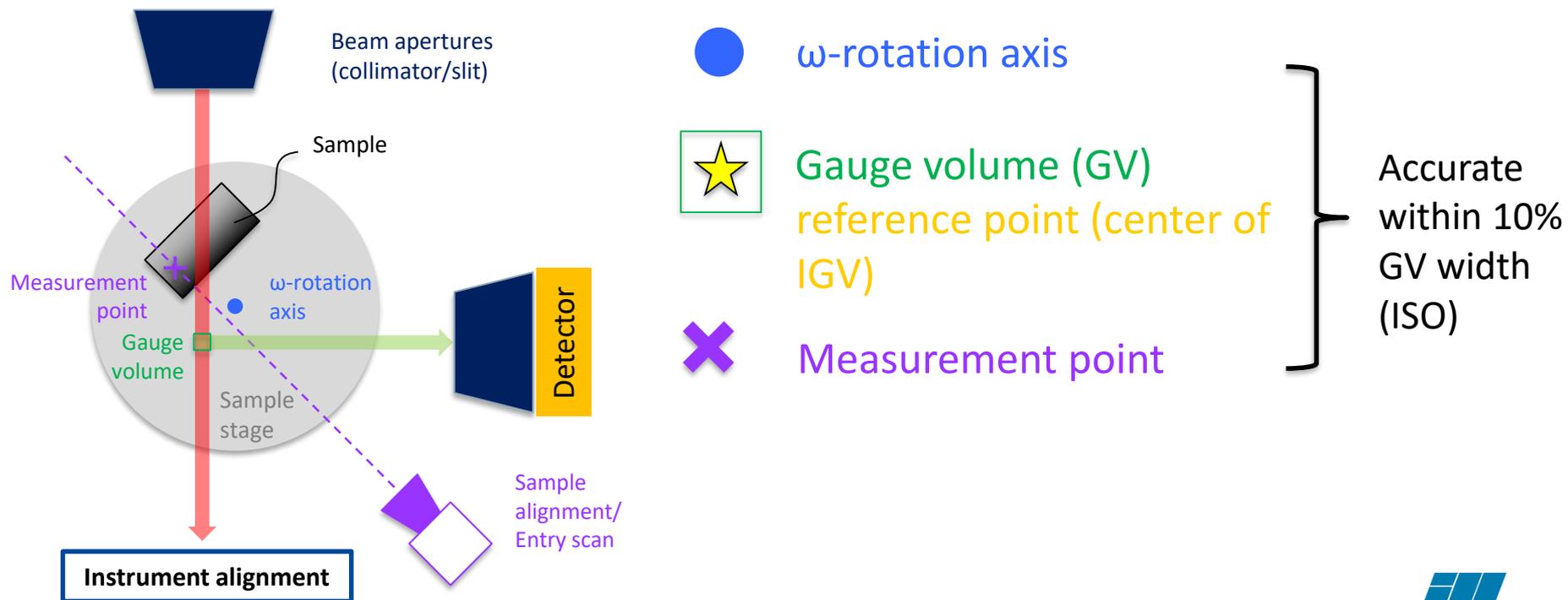
Neutron diffraction for stress determination

Technical overview

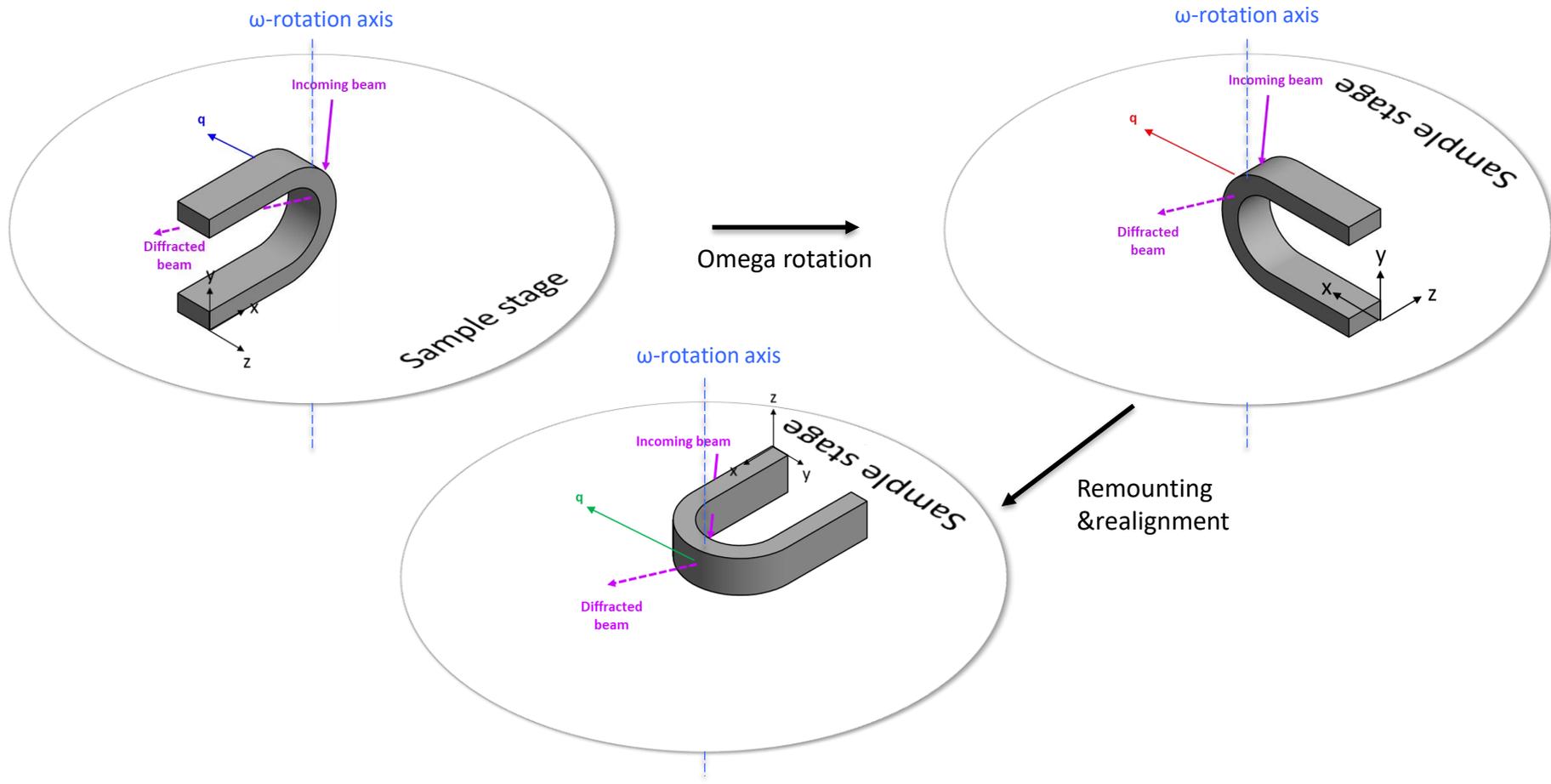


Neutron strain scanner & stress mapping

Technical overview

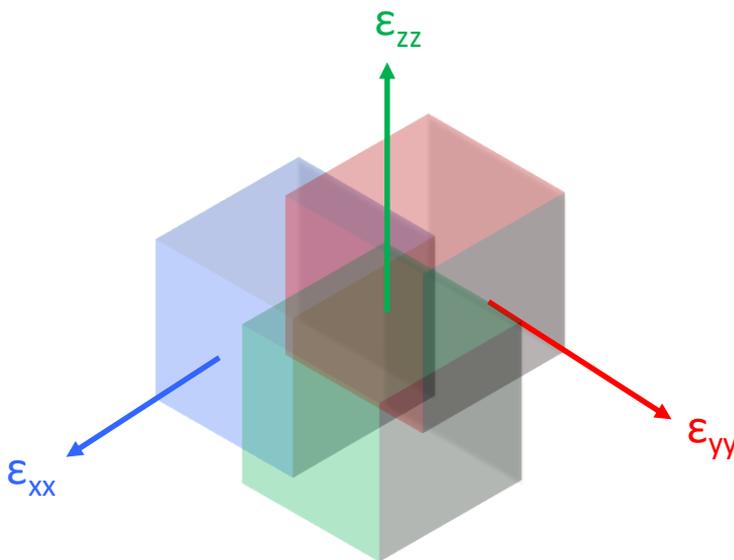
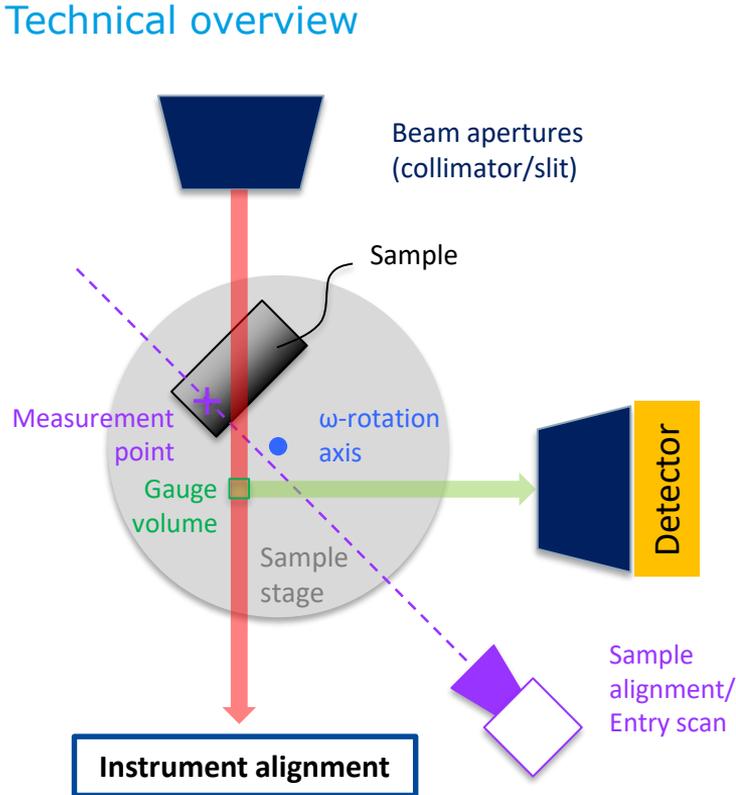


Neutron strain scanner & stress mapping



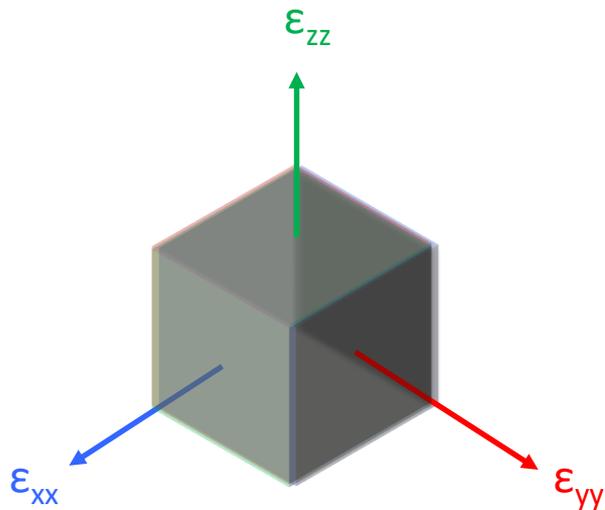
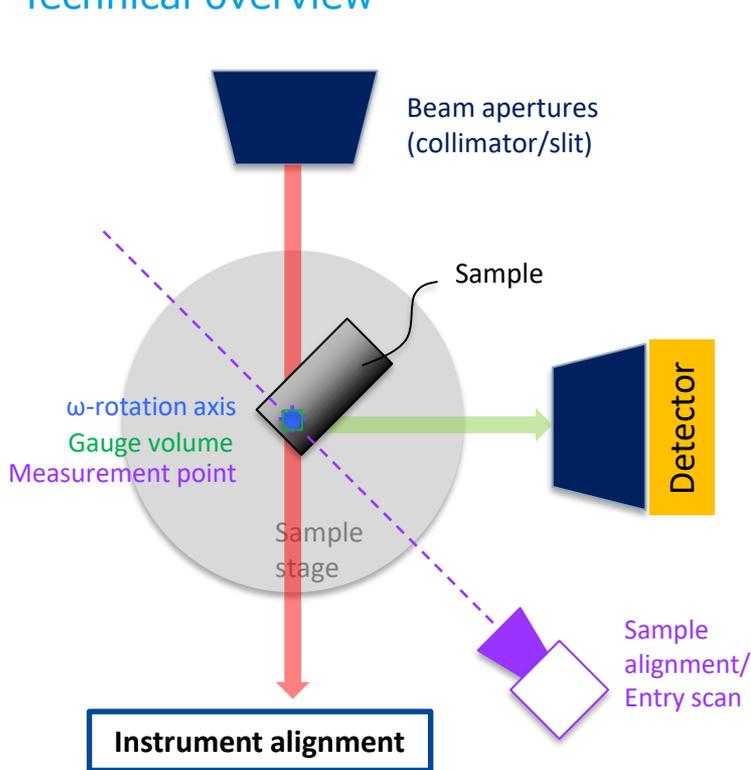
Neutron strain scanner & stress mapping

Technical overview



Neutron strain scanner & stress mapping

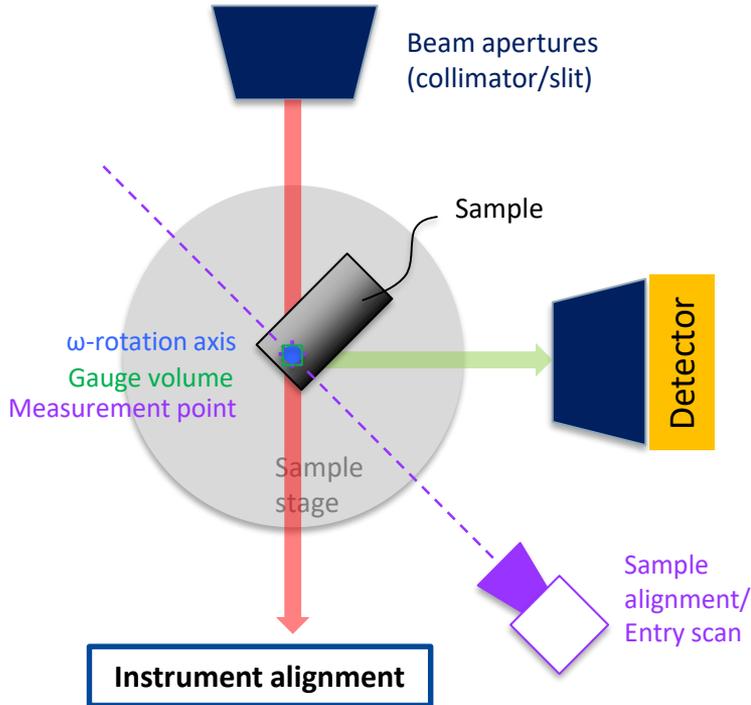
Technical overview



Positional accuracy is very important!

Neutron strain scanner & stress mapping

Technical overview



Development of possible methods to **characterise** particular setup of instruments →

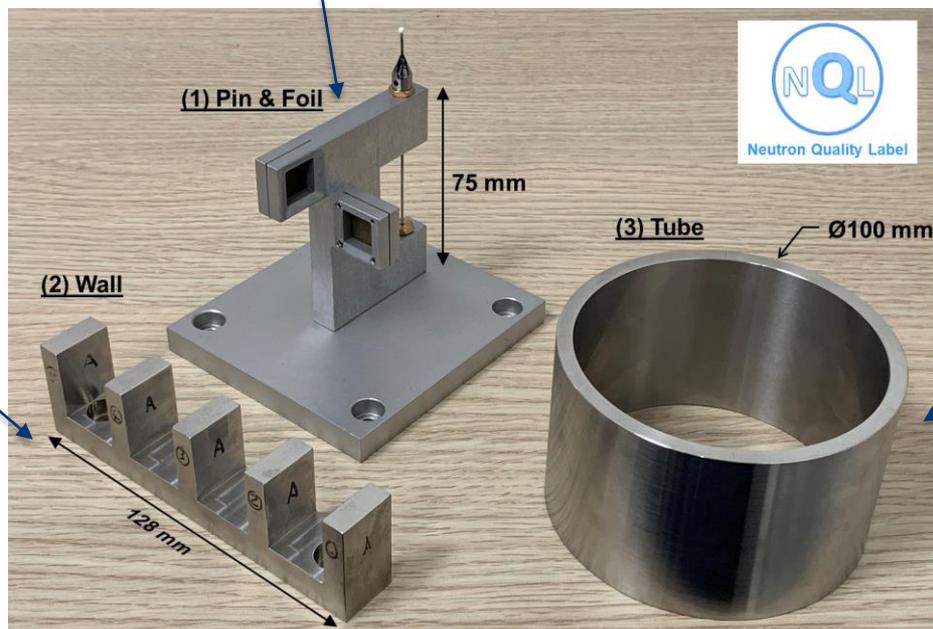
- **gauge volume centroid (reference point) vs ω -rotation axis**
- **precision of sample alignment using optical system**
- **accuracy of entry scan analysis software for sample alignment**

Calibration samples

Methods

Pin & foil calibration sample: orthogonal 0.3 mm foils, changeable + changeable pins → instrument alignment

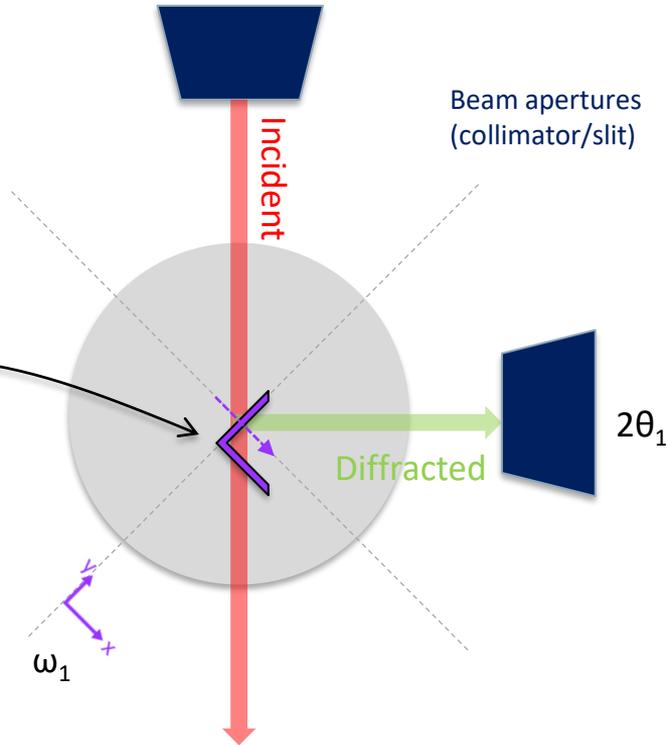
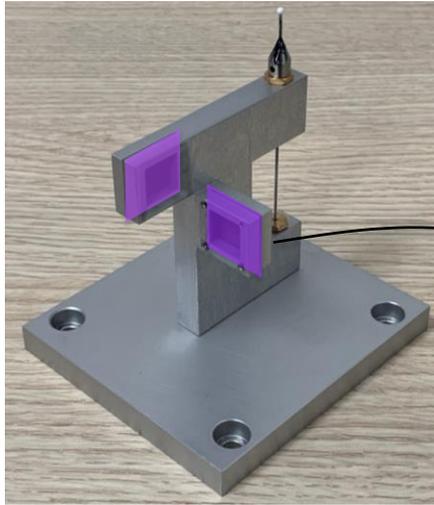
5-Wall sample: 5 equidistance walls → reproducibility of sample alignment, i) optical & ii) entry scan analysis on flat surfaces



Tube sample → sample alignment, entry scan analysis on curved surfaces

Instrument alignment: Pin and foil scans

Methods



Foil scans at different ω -angle

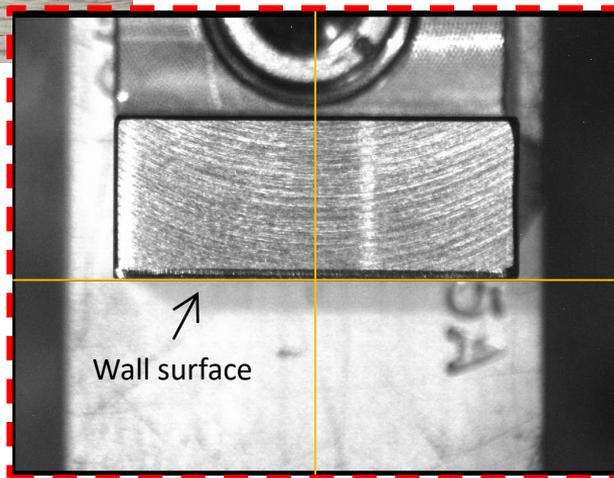
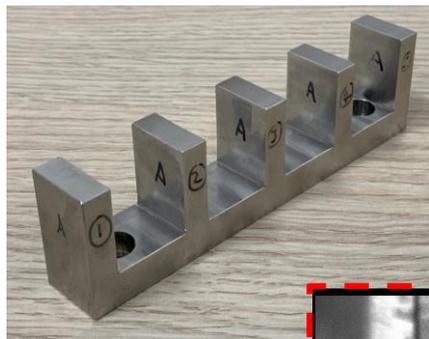
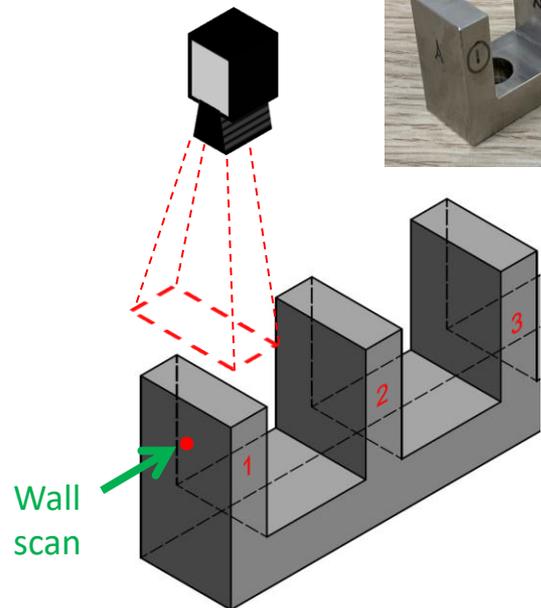


Characterise the rotation axis of ω relative to reference point (centre of IGV)

Sample alignments (optical): wall scans

Methods

Camera/
theodolite



Wall alignment position
vs wall position
determined with neutron

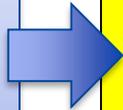


Characterise the
precision of
sample alignment
using optical
system

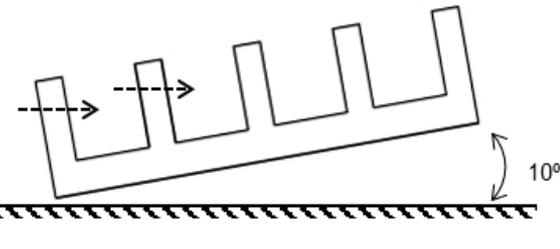
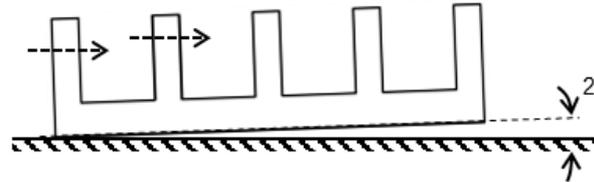
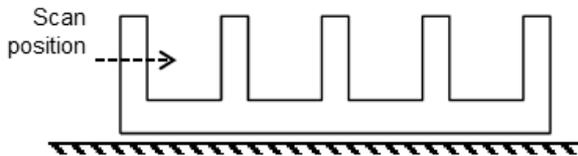
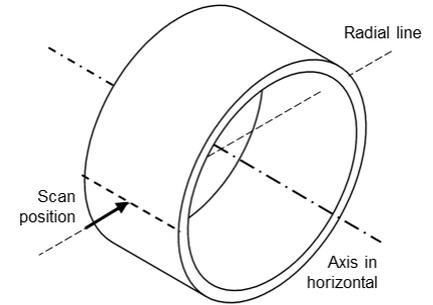
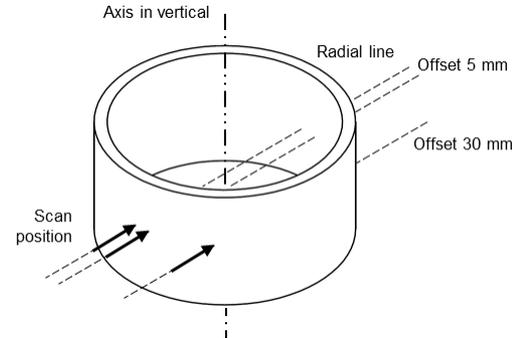
Sample alignments (entry scan): wall scans

Methods

Wall thickness determined with neutron vs CMM measurement (accuracy $<5 \mu\text{m}$)

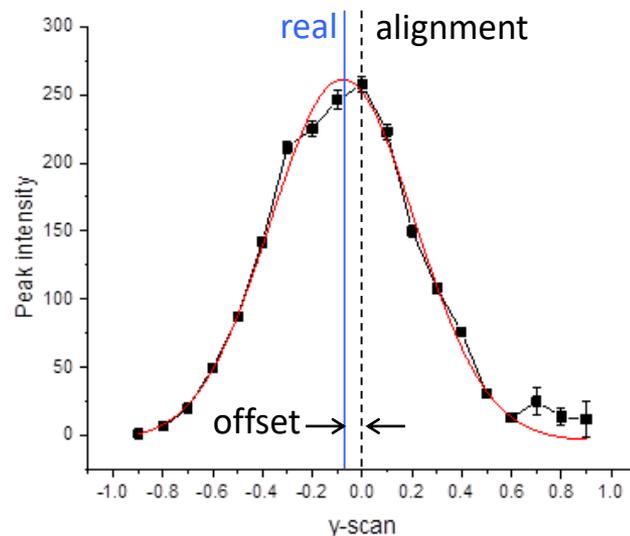
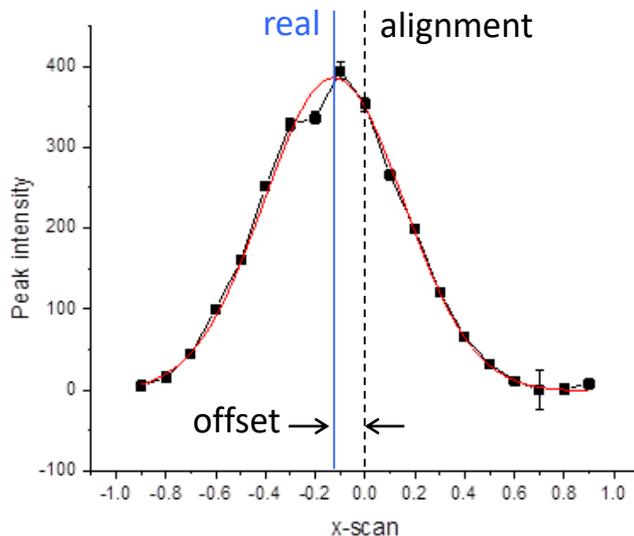
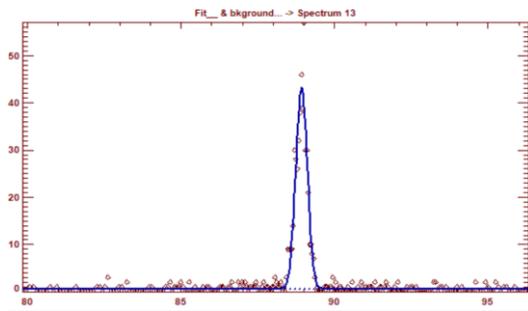
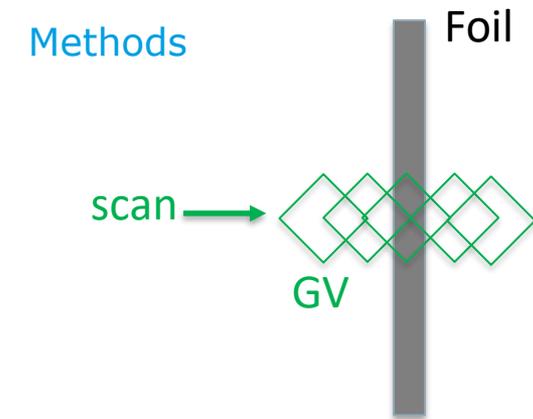


Characterise the accuracy of the entry scan analysis software for surface determination



Data analysis: Foil scans

Methods

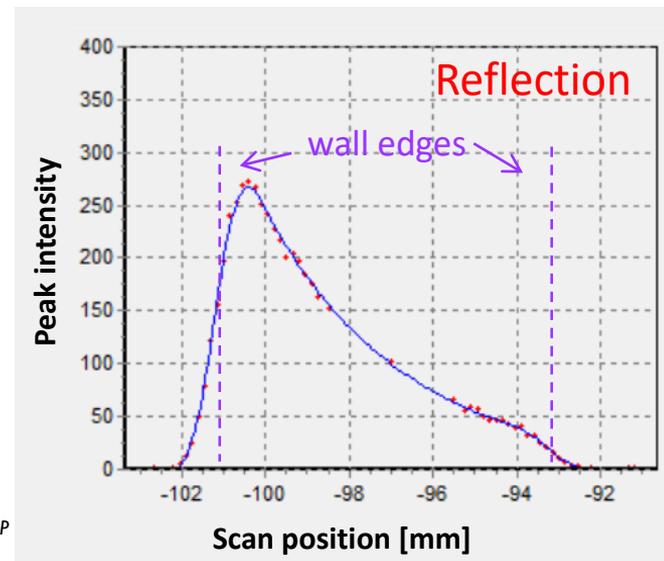
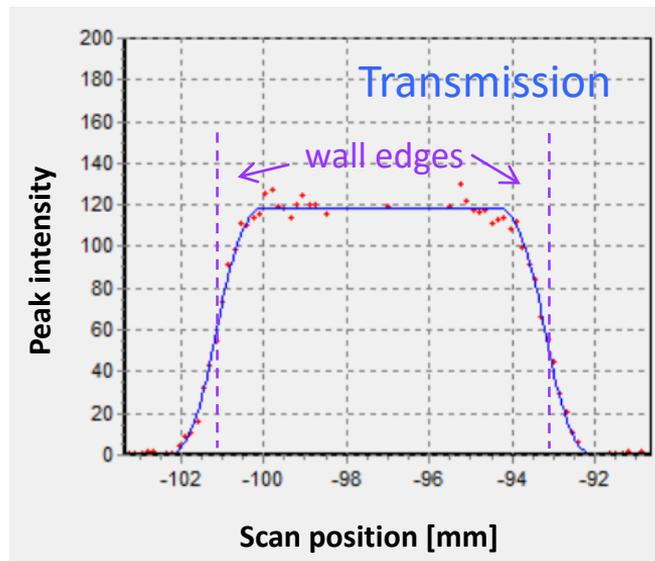
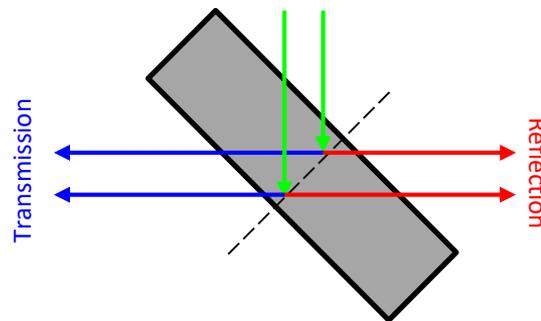
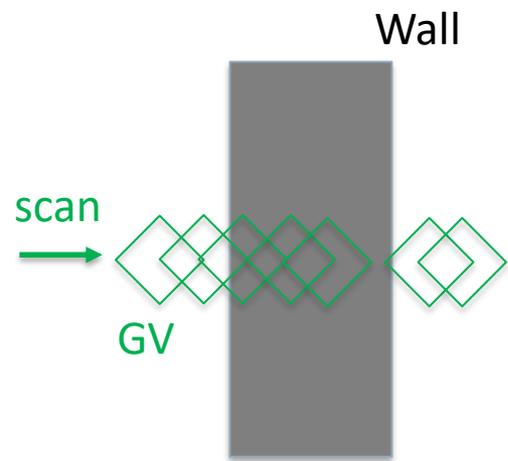


Peak intensity



Data analysis: Wall scans

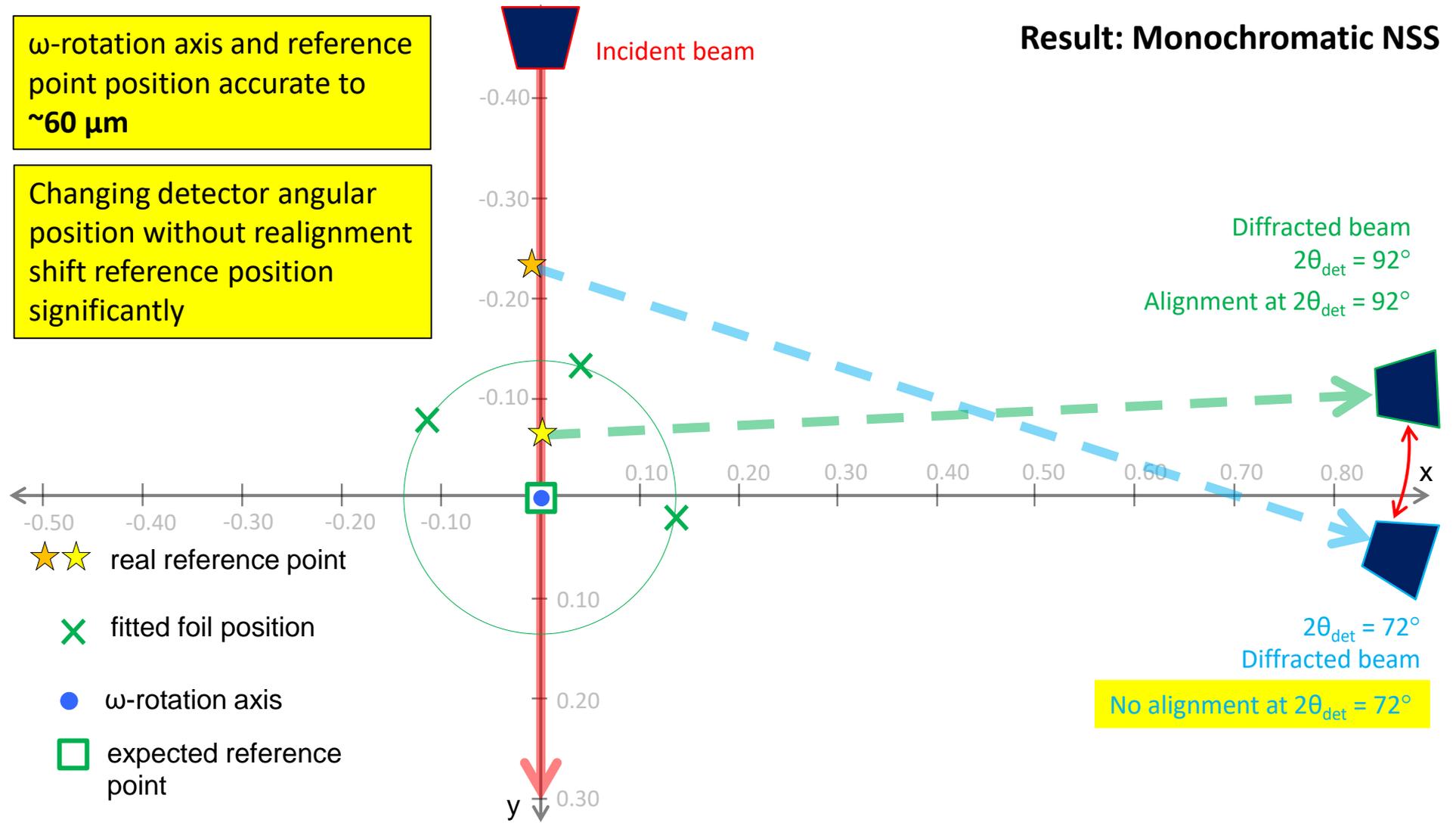
Methods



Result: Monochromatic NSS

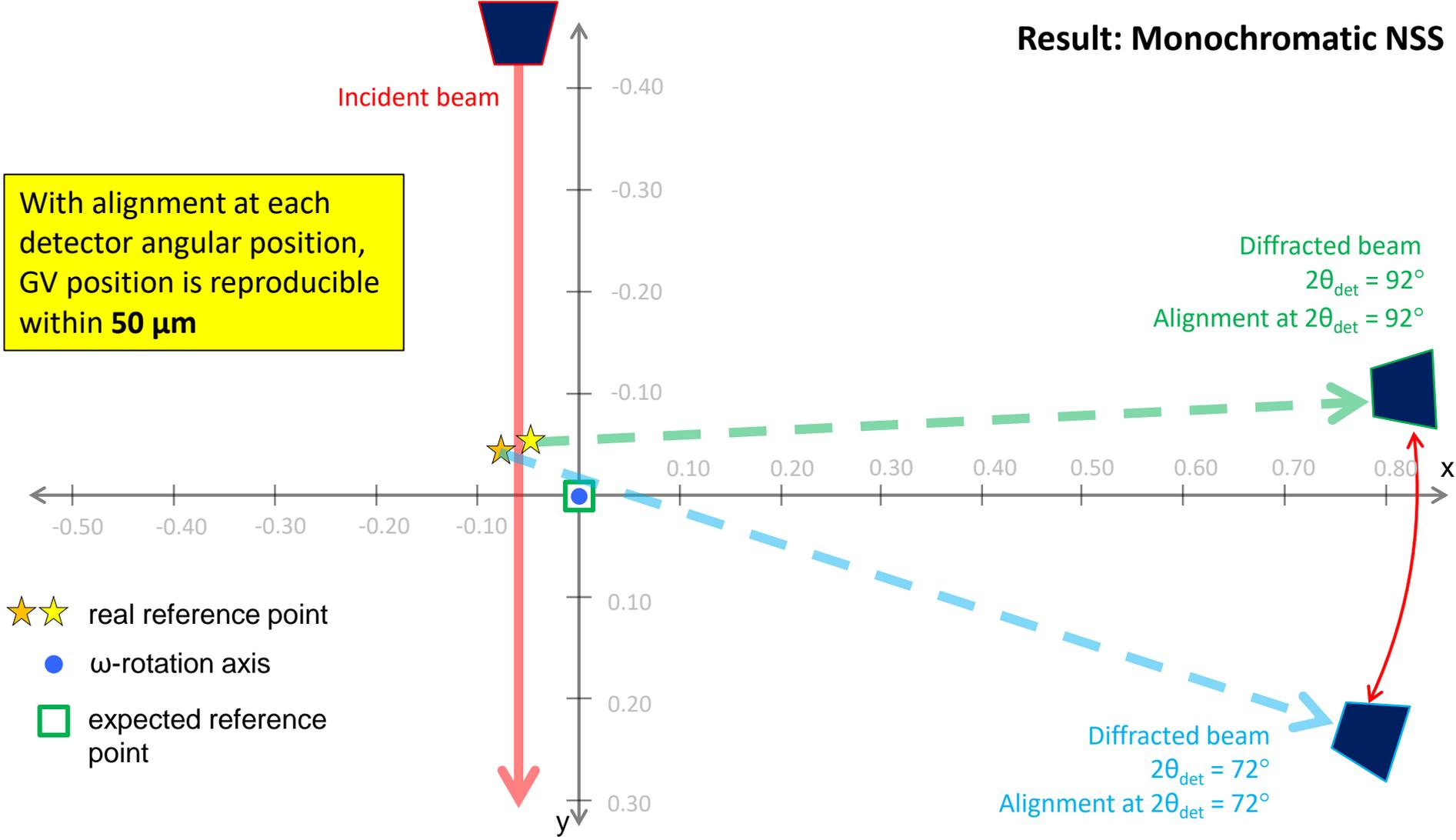
ω -rotation axis and reference point position accurate to $\sim 60 \mu\text{m}$

Changing detector angular position without realignment shift reference position significantly



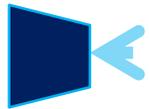
Result: Monochromatic NSS

With alignment at each detector angular position, GV position is reproducible within **50 μm**

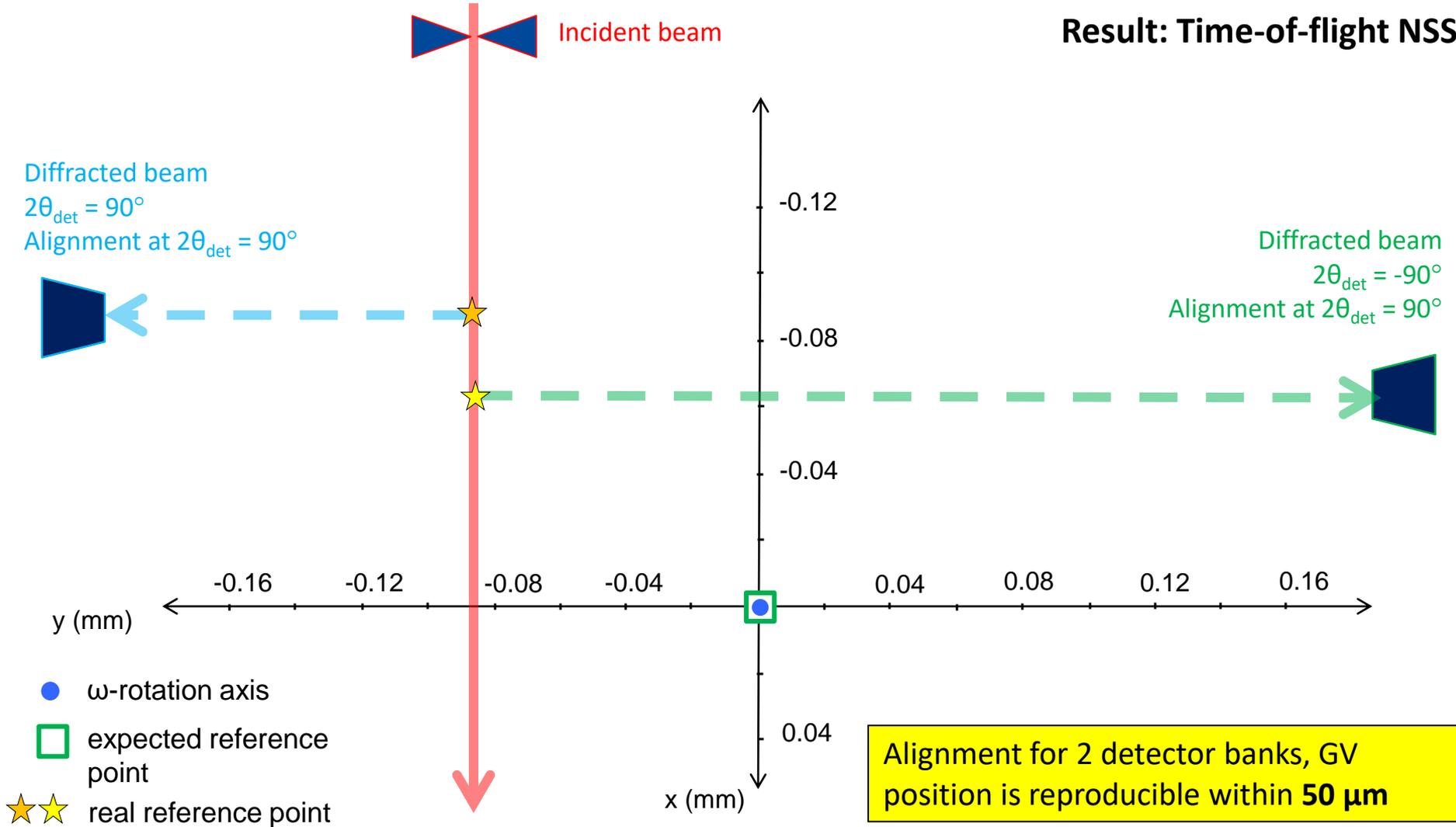
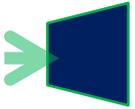


Result: Time-of-flight NSS

Diffracted beam
 $2\theta_{\text{det}} = 90^\circ$
Alignment at $2\theta_{\text{det}} = 90^\circ$



Diffracted beam
 $2\theta_{\text{det}} = -90^\circ$
Alignment at $2\theta_{\text{det}} = 90^\circ$



- ω -rotation axis
- expected reference point
- ★ ★ real reference point

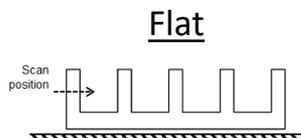
Alignment for 2 detector banks, GV position is reproducible within **50 μm**

Sample alignment

Result

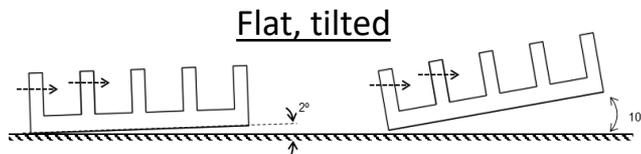
Reproducibility of sample alignment procedures (camera/ theodolite) → ~100 μm

Accuracy of entry scan for alignment:



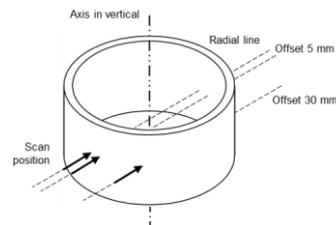
<100 μm

(Better than 10% of GV width)



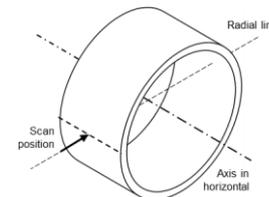
Can achieve 100 μm (10% of GV width) depend on GV height; taller GV worse accuracy

curved, axis vertical



Geometry model necessary, can achieve 100 μm (10% of GV width)

curved, axis horizontal

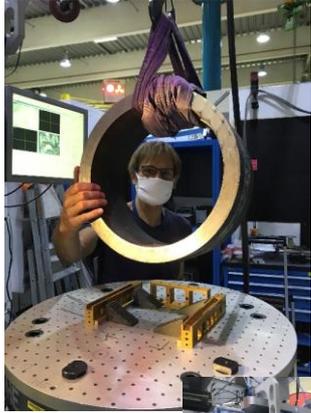


Simple model can achieve 100 μm (10% of GV width) depend on GV height

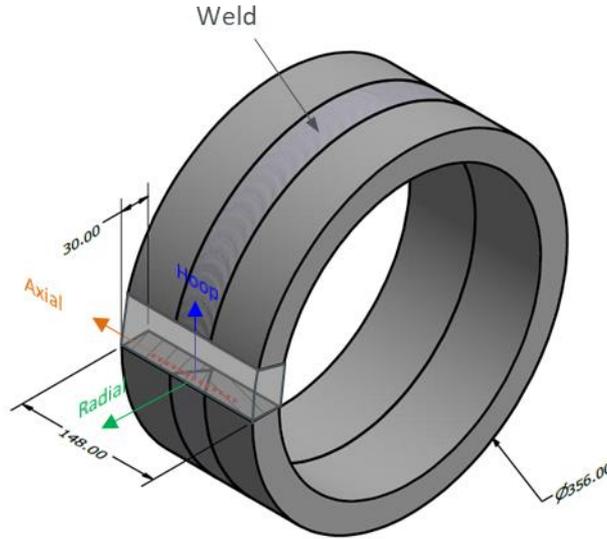
Conclusion

- A possible common method for evaluating positional accuracy of the NSS has been proposed
- Benchmarking results showed participating NSS setup has comparable numbers → agree with VAMAS TWA20 results and ISO guidelines → sufficient for many engineering application
- Other instruments are invited to join and attain the NQL

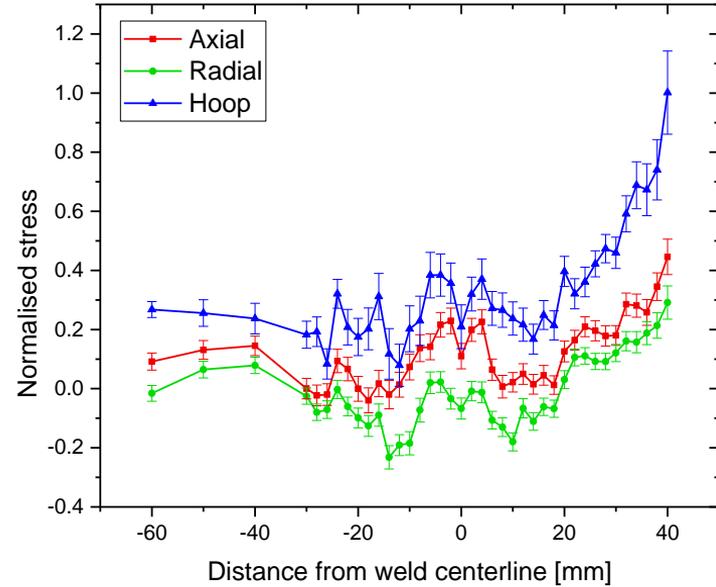
Next step...



Measurement of
engineering samples with
industrial partners



..... Measurement points



Contributors

brightness²



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