

# Target system commissioning

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Neutron source section members

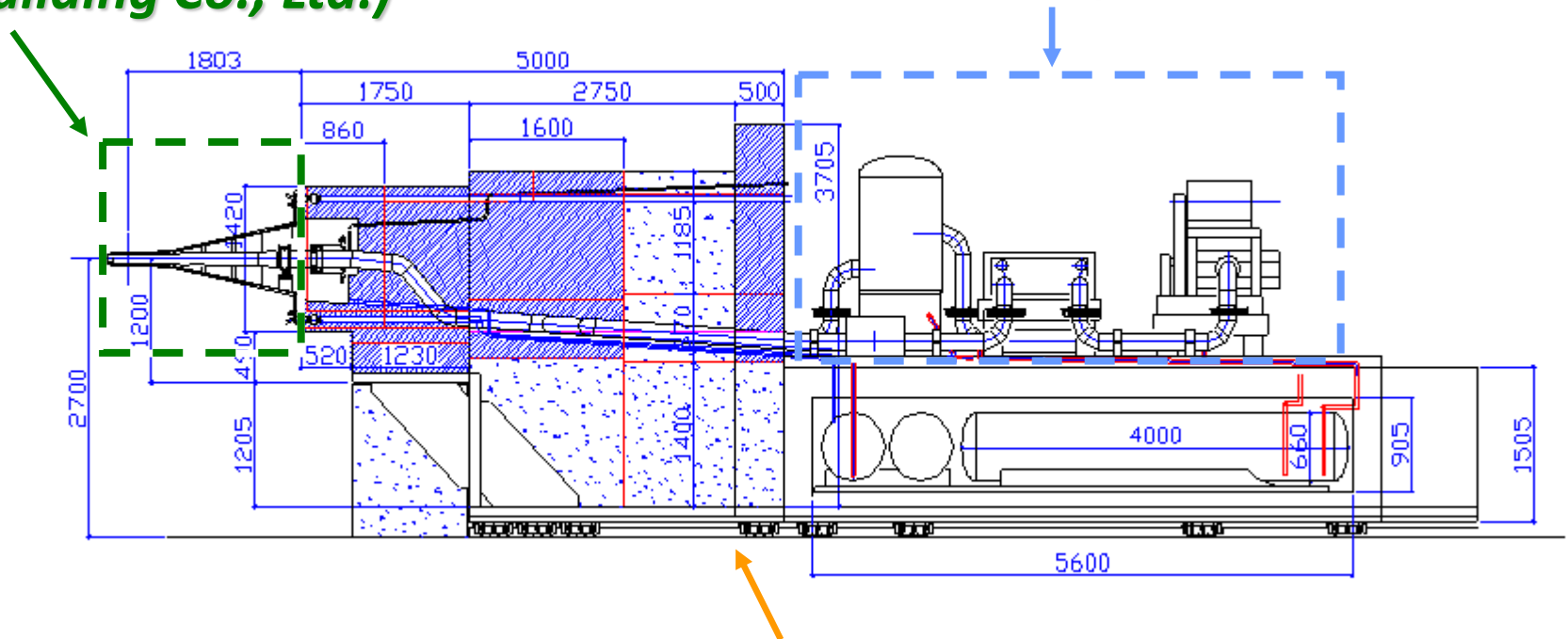
J-PARC center

# Mercury target system

Mercury target system consist of 3 subsystems

**Mercury target vessel**  
(Mitsui Engineering & Shipbuilding Co., Ltd.)

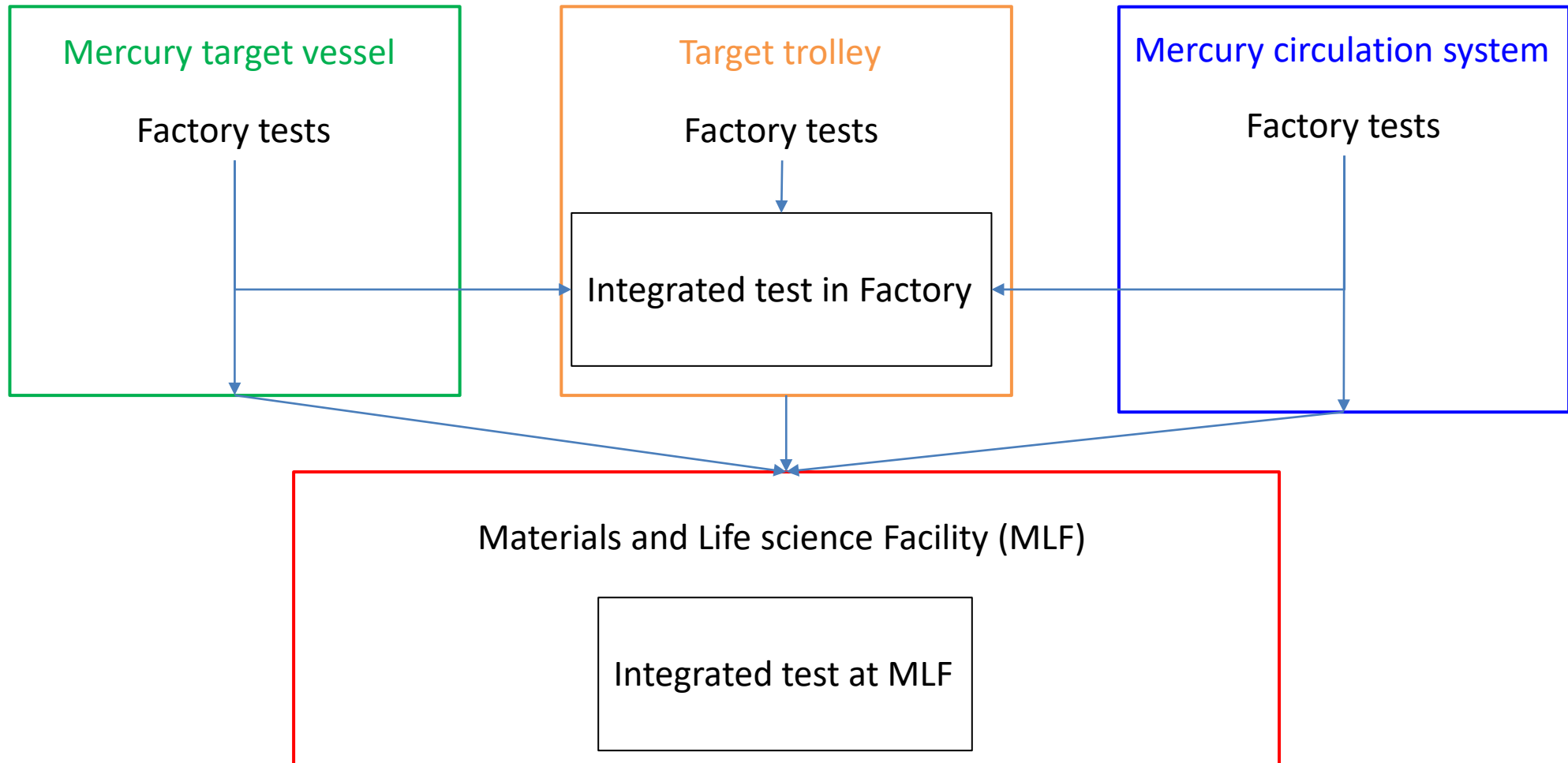
**Mercury circulation system**  
(Kawasaki Heavy Industries, Ltd.)



**Target trolley** (Fuji Electric Systems Co., Ltd.)

Each subsystem was fabricated by different manufacturing companies.

# Commissioning flow



After passing factory tests, 3 subsystems were assembled in the factory and integrated test were carried out. After that, Mercury target system were installed in MLF, and integrated tests were carried out.

## Subsystems

Mercury target vessel

Mercury circulation system

Target trolley

Each manufacturing company  
carried out subsystem test

### Common items

- Visual inspection,
- Material inspection,
- Dimensional inspection,
- Gas leakage test,
- Sensor calibration,
- Exchangeability of the components, etc.



## Integrated system test

### Check points in the integrated test in factory

- Connection among subsystems  
Dimension, gas leakage, etc.
- Exchangeability of each component  
No interference among subsystems

# Integrated system tests in MLF

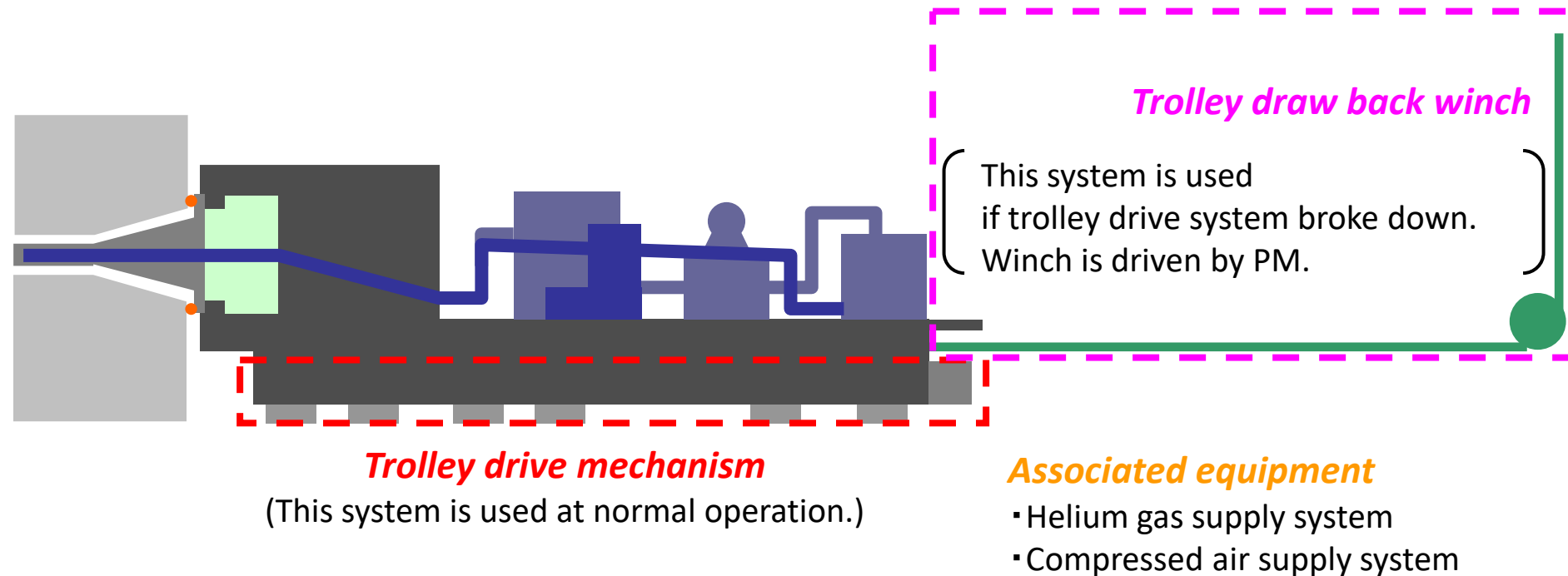
After passing the integration system test in factory, JAEA carried out all integrated system tests.

Check points in the integrated test in MLF

- Connection among subsystems  
Dimension, seal performance, etc.
- Exchangeability of each component by using the remote handling system in MLF  
No interference among subsystems and remote handling system
- Target trolley operation
- Mercury circulation
- Interlock system

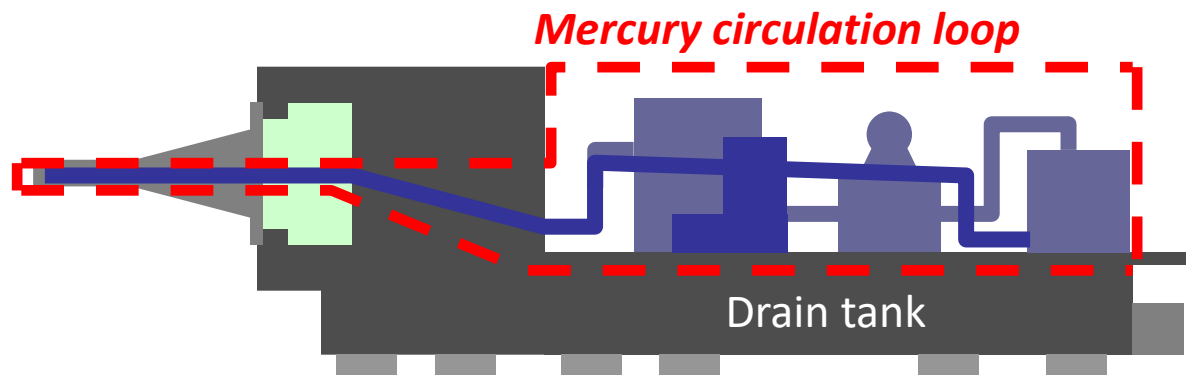
# Target trolley tests in MLF

	Item	Check point
<b>Trolley drive mechanism</b>	Motion	Position control of target trolley Motion of cable veyor
	Lock	Work of stopper
<b>Trolley draw back winch</b>	Forced draw back	Possible or not



# Mercury circulation test

Item	Check point
Vacuum in the loop	Operation time Degree of vacuum
Filling mercury in the loop	Operation time
Mercury circulation	Flow rate (Max. flow rate : 50 m <sup>3</sup> /s) Leak from joint (e.g. mercury pipe connection system)
Emergency stop	Influence of circulation system (e.g. mercury hammer )
Draining mercury to Drain tank	Operation time



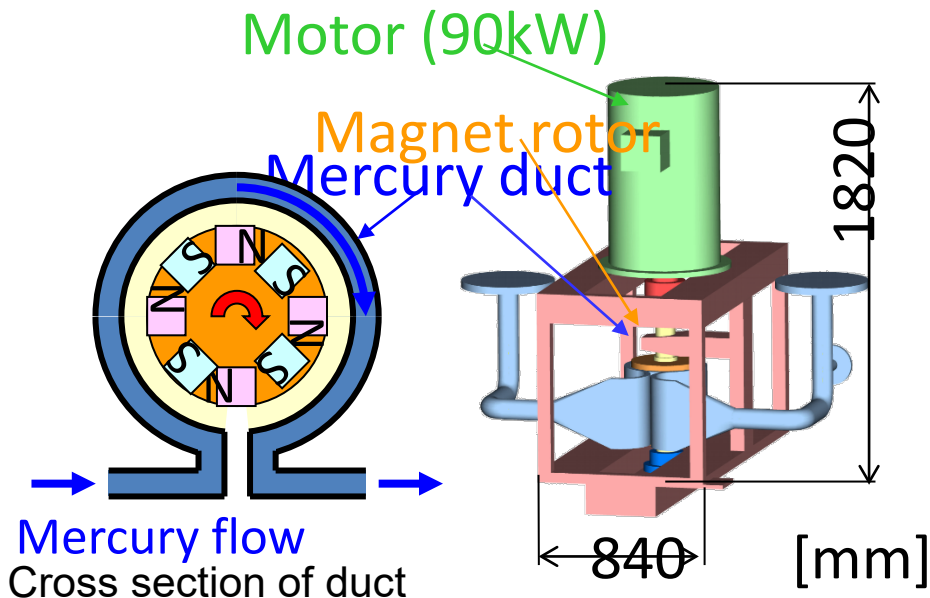
## Associated equipment

- Helium gas supply system
- Helium gas exhaust system
- Gas waste processing system
- Secondary water cooling system (Mercury heat exchanger)

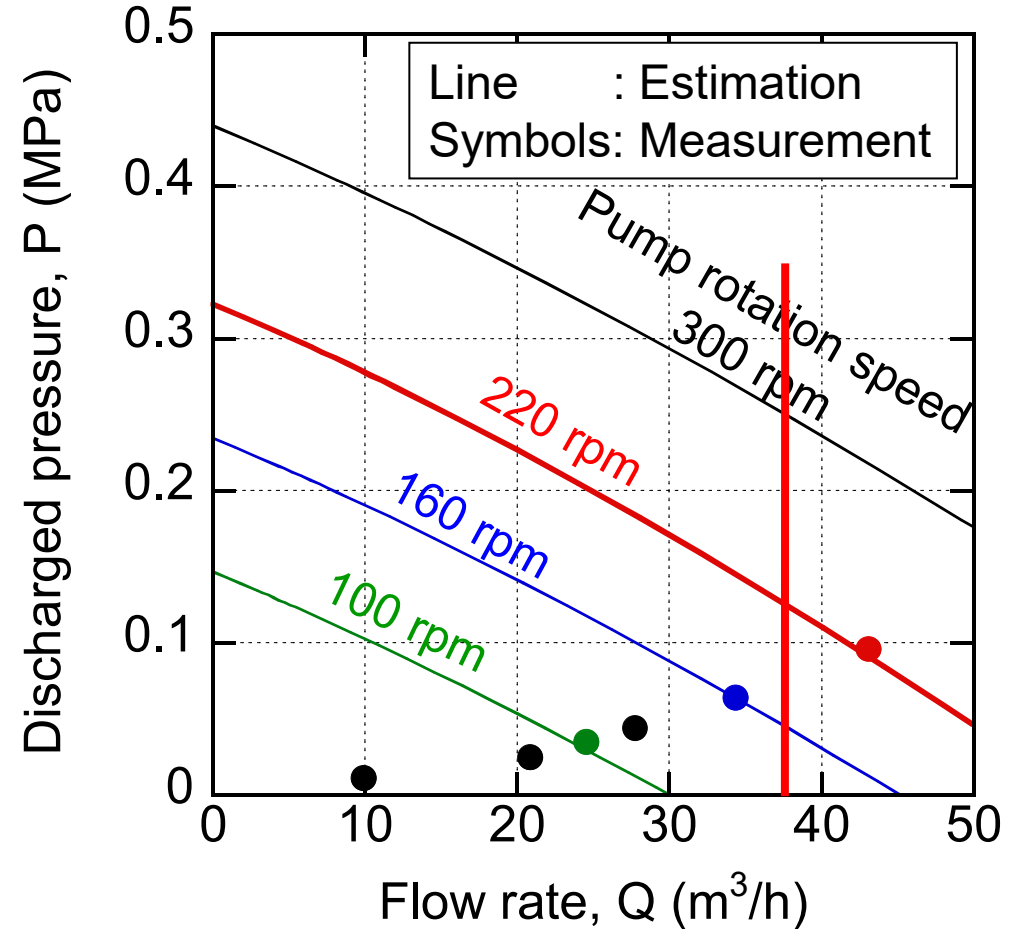
# Mercury circulation

## PM pump

Permanent Magnet rotating type induction pump that was changed from gear pump because risk against mercury leakage is the lowest in the PM pump.



We confirmed pump ability which was similar with estimation, and PM pump could flow mercury with sufficient flow rate.

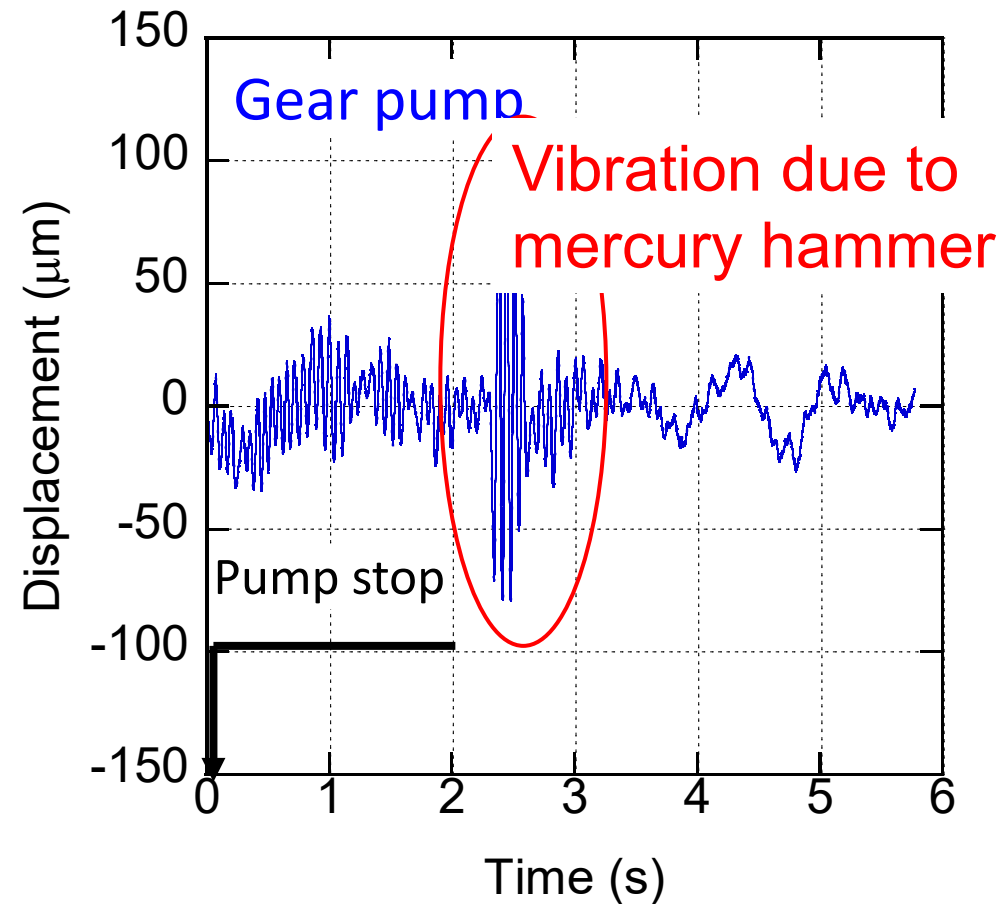
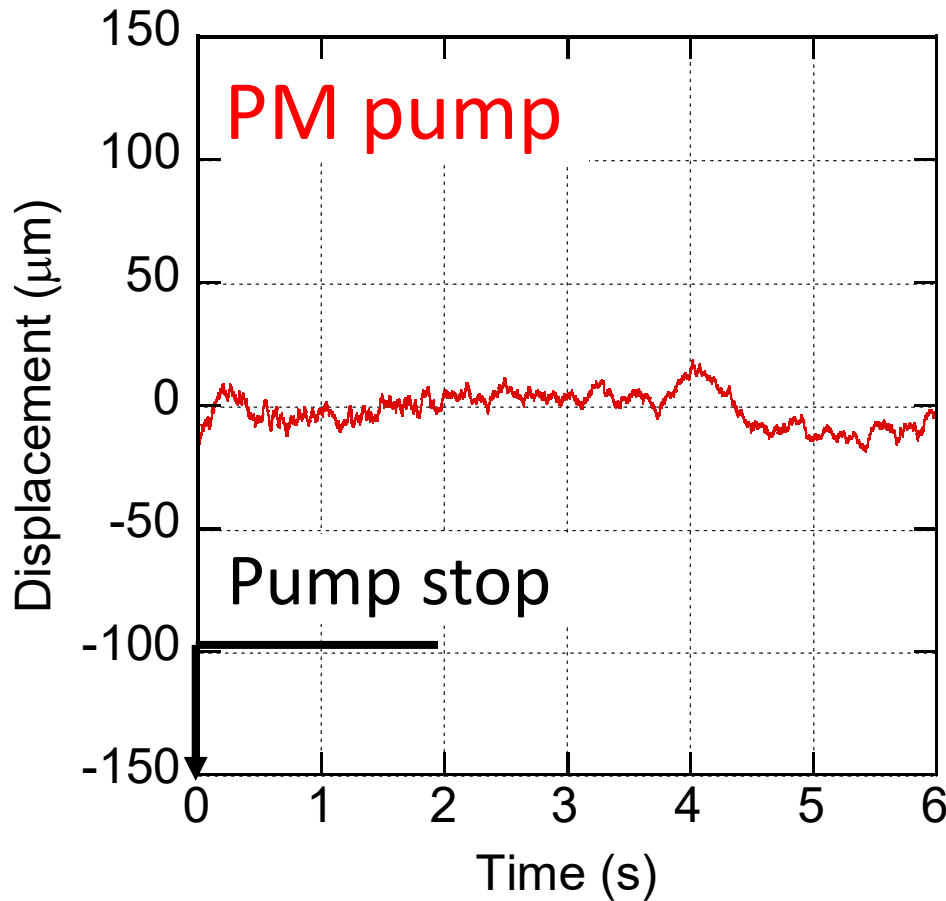


Required flow rate for 1 MW proton beam operation (38 m<sup>3</sup>/h)



# Mercury hammer

Vibration of the pipe was measured after pump stop to investigate mercury hammer when the electric power loss occurs.



Hammer does not occur in the PM pump because there are no disturbance to flow.

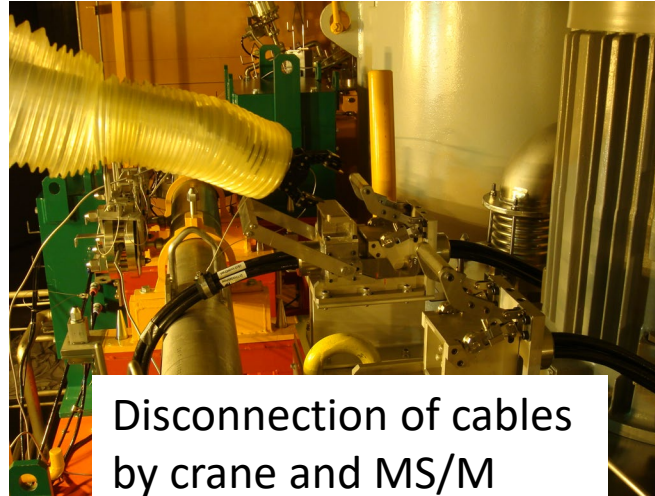
# Exchangeability of components

Mercury target vessel, PM pump, heat exchanger, sensors, etc.

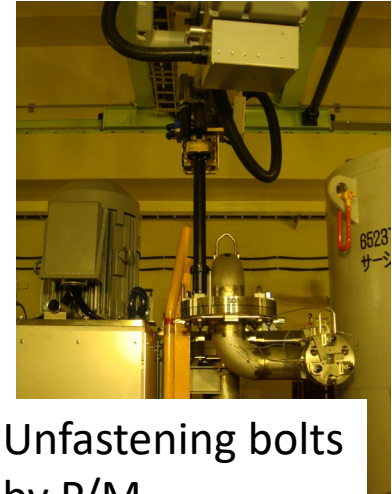
## Exchanging state of PM pump



Installation of new pump into hot cell



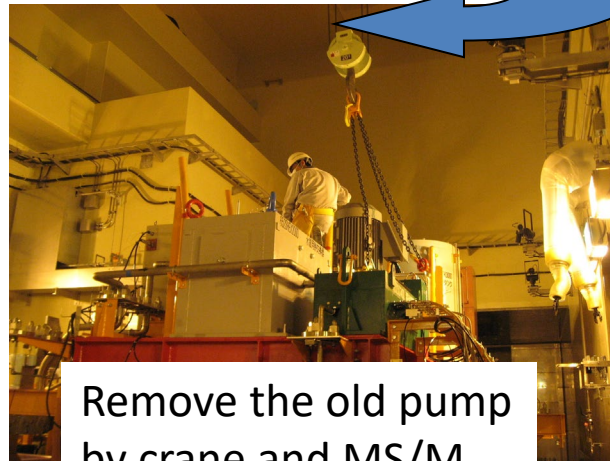
Disconnection of cables by crane and MS/M



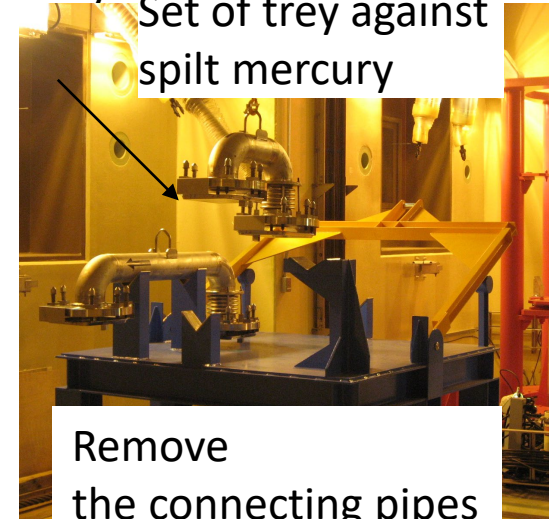
Unfastening bolts by P/M  
Set of tray against spilt mercury



Set new pump  
Set of pipes by crane and MS/M  
Fastening bolts by P/M  
Connection of cables by MS/M



Remove the old pump by crane and MS/M

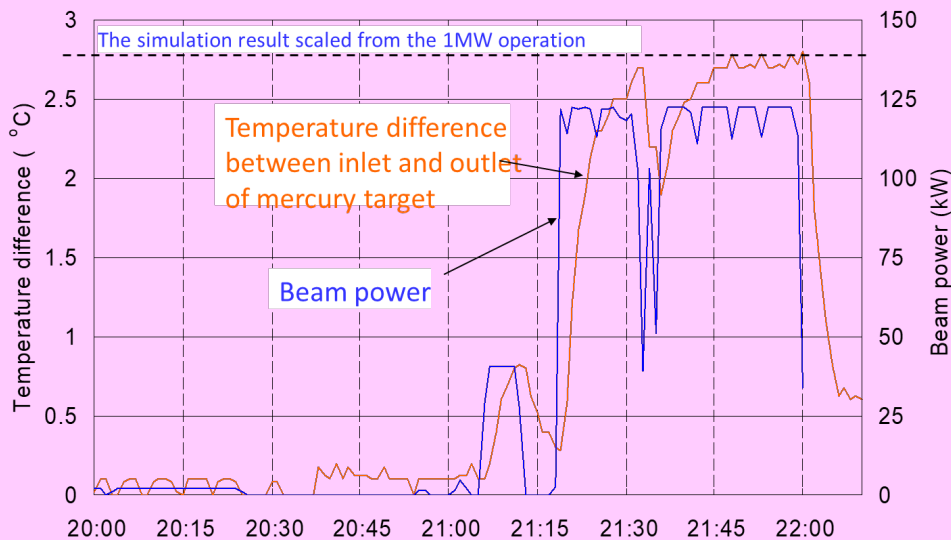


Remove the connecting pipes by crane and MS/M

# In beam test

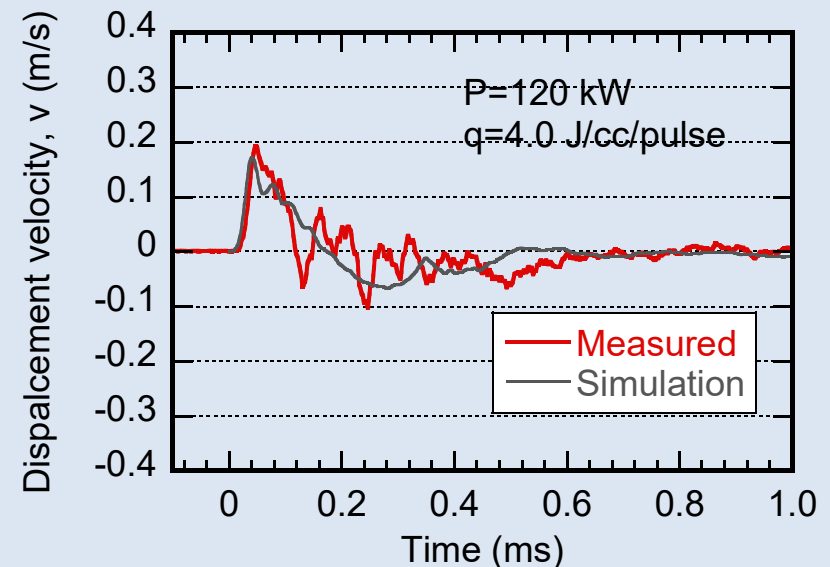
- Mercury temperature raise between inlet and outlet of target vessel.
- Vibration of the mercury target vessel due to the pressure waves.

For validation of the simulation that was used for the design



Mercury temperature increased 2.8 °C in 120 kW beam operation.

That agreed with the simulation result which was scaled from 1 MW beam operation.



The measured vibration agreed well with estimation which was obtained by simulation.

# Summary

- Mercury target system consists of 3 subsystems.
- Each subsystem was fabricated by different companies.
- After passing subsystem test, subsystems are integrated and the integrated system test was carried out.
- And then, subsystems were assembled in MLF.
- In MLF, we check
  - Connection among subsystems (Dimension, seal performance, etc.)
  - Exchangeability of each component by using the remote handling system in MLF (No interference among subsystems and remote handling system)
  - Target trolley operation
  - Mercury circulation
  - Interlock system etc.
- In in-beam test, we validated the simulation used for the design.