

SSS Mechanical Interface Reference Document

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Goals



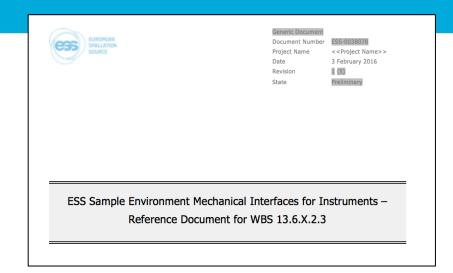
- Allow rapid, accurate, repeatable installation of sample-environment equipment (SEE).
- Maximise potential for sharing SEE between instruments
 - widest scientific scope for users
 - redundancy in case of equipment failures

This requires standards





Mechanical Interfaces Handbook



ESS-0038078 available on CHESS and CONFLUENCE:

https://ess-ics.atlassian.net/wiki/display/SA/Feedback+here+from+instrument+teams

Requirements for:

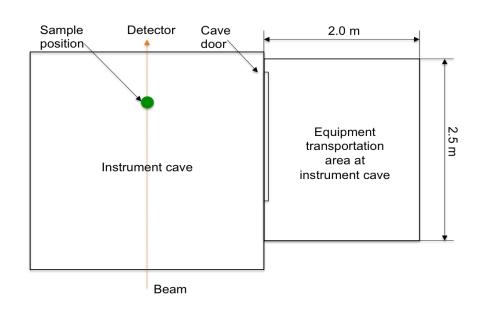
- 1) Space
- 2) Mechanical positioning
- 3) Magnetic considerations

Focus here on general concepts



Space – general requirements

Access

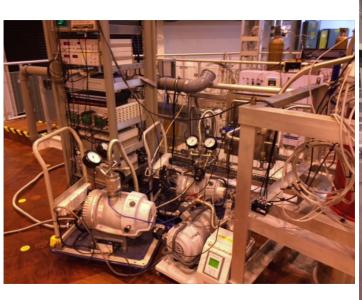


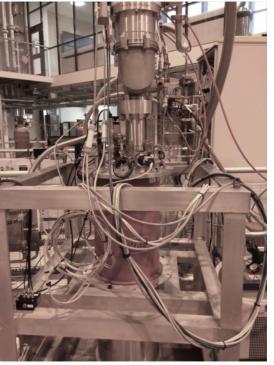
Need a clear area of **2.0** x **2.5**m adjacent to instrument entrance (may be on the roof for a top-loader).





Space for ancillary equipment





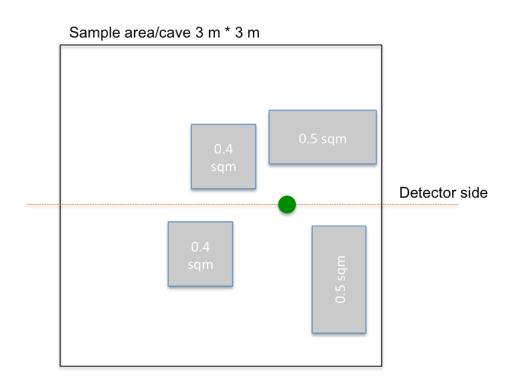




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Space – general requirements

Space for ancillary equipment



4 areas required:

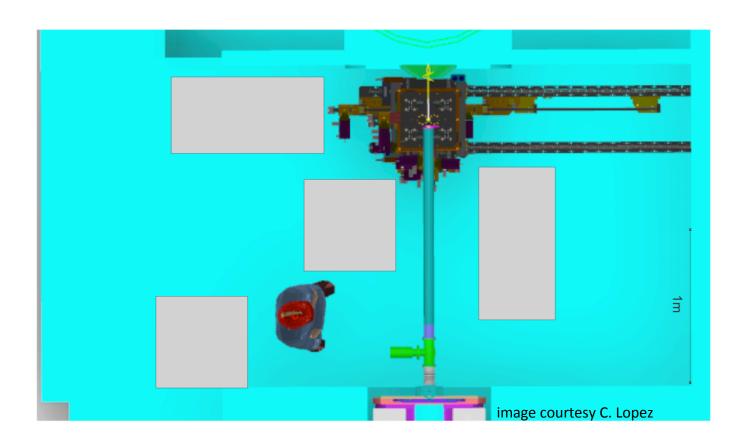
- 2 x 0.5m²
- $2 \times 0.4 \text{m}^2$

75% shall be free floor area



Space – general requirements

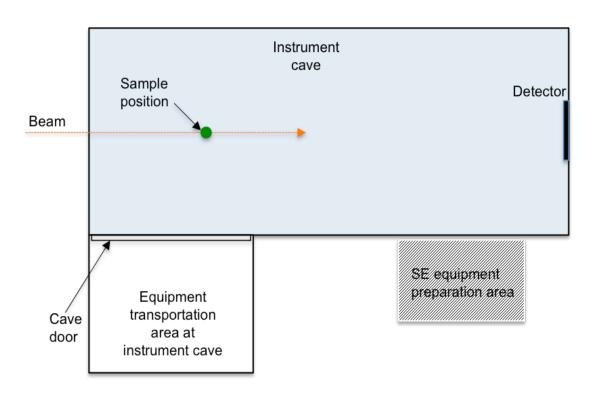
Space for ancillary equipment: LOKI example





Space – general requirements

Preparation area



2m x 3m made available at or within 20m of instrument





Sample environment comes in all different shapes

and sizes

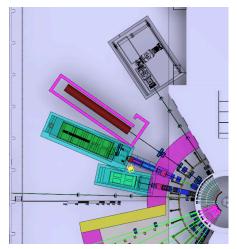






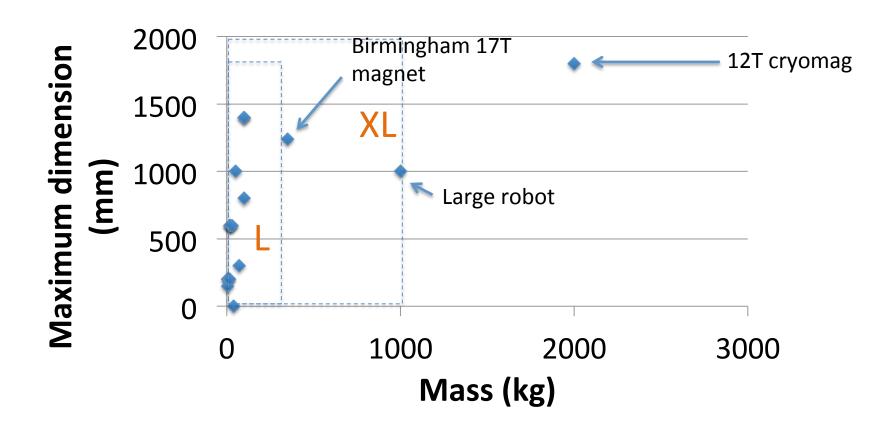


• As do instruments...





Space – instrument specific



Define two compliance standards: L and XL





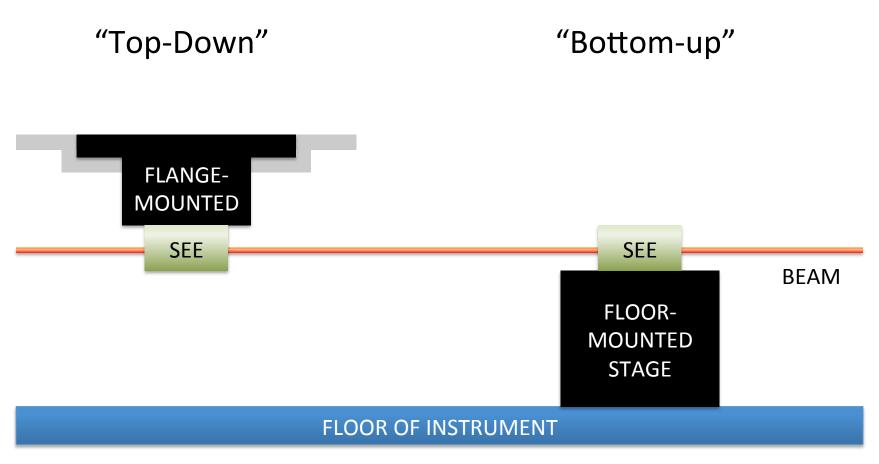
Appendix A lists compliance standard for each item of SEE

Equipment	Weig ht (kg)	Shape	COG	Max tilt (Degrees)	Width (X)/ Diameter (mm)	Length (Y) (mm)	Height (mm)	XL /L	Required Peripherals/com ments
General									
Rotating sample holders	< 20							L	
Rheometer	20							L	
Langmuir Trough	< 20		Below half height					L	
Robot	30- 1000 kg	Spherical						XL	Size dependent on reach required.
Linear sample changer	< 50	Rectangular box	Half height		500	1000	400	L	Z table, cooler
Temperature/Field s/Temp									
Pulsed Tube Refrigerator (PTR)	40	Cylinder	Top heavy	No restrictions but performance changes	150	150	600	L	2*Vacuum pumps compressor



Space – instrument specific

Also considered two mounting scenarios*:



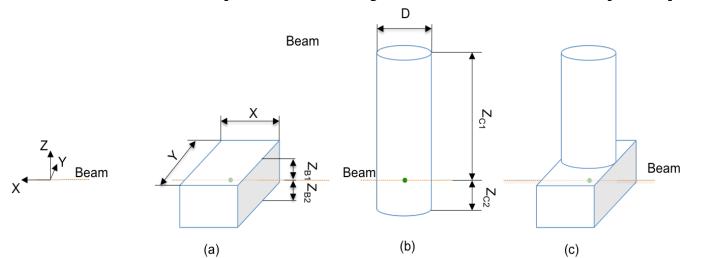




There this gives 4 possible configurations:



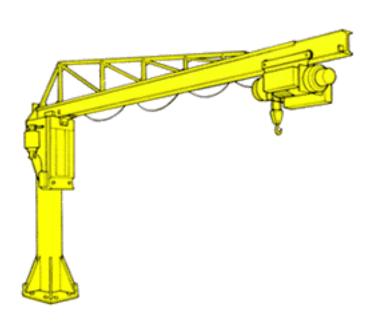
Determines requirements for minimum sample space



Mechanical positioning



Cranes



Availability of a crane is required to transport SEE to sample position.

Requirement for dedicated instrument cranes*.

Capacity dictated by chosen compliance standard:

> 300 kg (L)

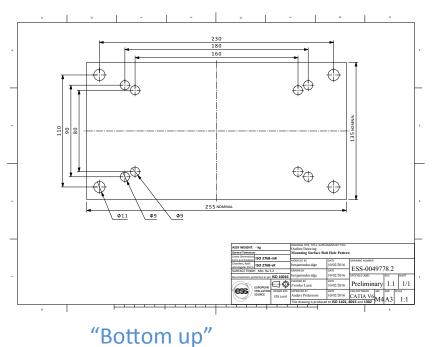
> 1000 kg (XL)

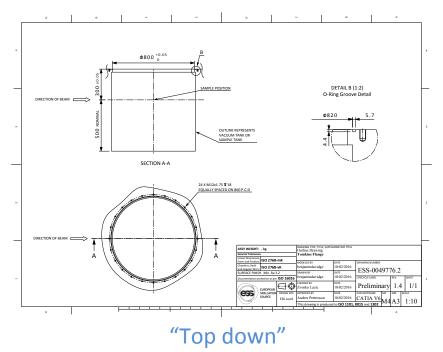
Mechanical positioning



Mechanical mounting

Conceptual design for mounting systems for BU & TD instruments:





- Pursuing kinematic design allowing calibrated offline alignment of SEE
- Requirements on mount-beam distance.
- Load capacity also specified: 300kg (L), 1000 kg (XL).



Magnetic considerations

Special requirements for instruments using magnetic SEE

Requirements depend on four service levels of instrumentation:

Level	Description
0	Spin echo
1	Electromagnet
2	<10T cryomagnet
3	>10T

- Distinct requirements for each service level described in Appendix C
- For level 2 and above no magnetic material within 2m of sample position

Magnetic considerations



Generic Document

Document Number Date ESS-0038078 Aug 26, 2015

Appendix C

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Reason	Power law* B ^m /r ⁿ	Approx. range (for level 3) Scale as B ^{m/n}	Affected item	Effect	Mitigating action	Require for service level (0-3)
Magnetic forces (unsaturated, dipole approx.)	B^2/r^7	0-1m	Cryomagnet, nearby objects	Quench, damage, injury, death	No magnetic material allowed <1m from magnet Force test in position on first use and after any modification.	2
	B^2/r^7	1-2m	Moveable magnetic objects	Pulled towards cryomagnet (see <1m)	Remove or fix in position	2
	B^2/r^7	> 2m	Moveable magnetic objects	Equilibrium positions disturbed	Remove or fix in position	2
	B^2/r^7	<5m	Reed switches (including pacemakers!!!)	Erroneous readings, malfunction	Use alternative, distance, warning signs	2
Magnetic forces (permanent magnets / saturated ferro- magnets)	$\frac{B}{r^4}$	0-1m	Motors, encoders, magnetic bearings	Failure, damage	Move further away	2
	$\frac{B}{r^4}$	1-5m	Motors, encoders, magnetic bearings	Potential malfunction, failure, damage	Test for resilience, shield, move away	2



Exact requirements are still being refined

 Please consider implications for your instruments and give feedback

Requirements formalised by end of March.